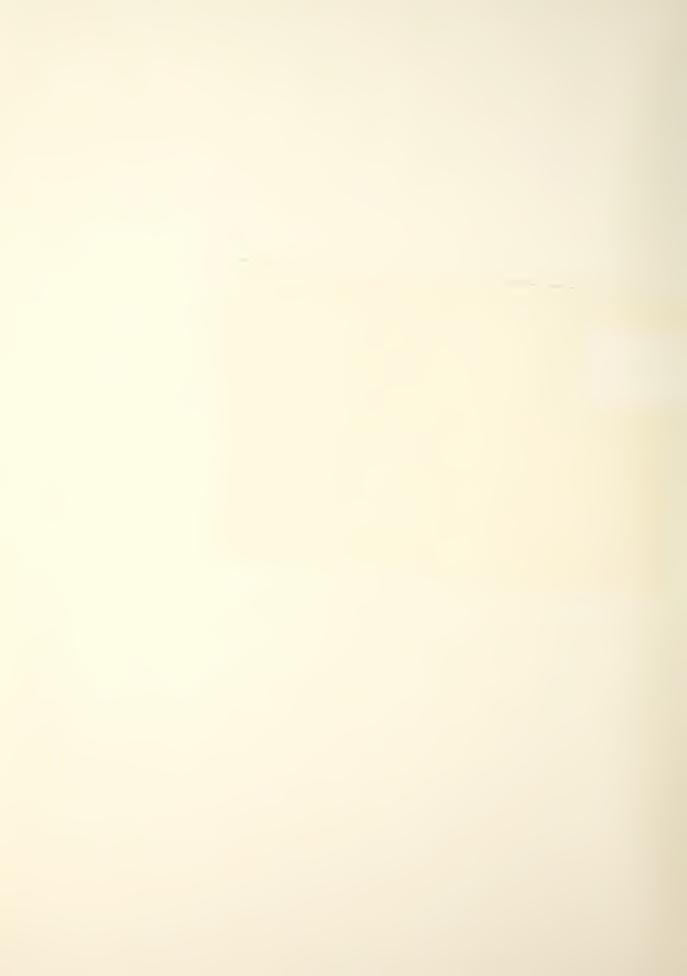


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NAVAL POSTGRADUATE SCHOOL Monterey, California



THESIS

AN INTERACTIVE COMPUTER INTERFACE WITH A DIGITAL RECEIVER

by

William Glenn Borries
March 1977

Thesis Advisor:

S. Jauregui

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An Interactive Computer Interface with a Digital Receiver

by

William Glenn Borries Lieutenant, United States Navy B.S., United States Naval Academy, 1970

Submitted in partial fulfillment of the requirements for the degree of

MASTER OF SCIENCE IN ELECTRICAL ENGINEERING

from the

NAVAL POSTGRADUATE SCHOOL March, 1977 RAILS C.

ARSTRACT

A computer interface to connect both the Applied Technology Airponne Computer (ATAC) and the KIM-1 Microprocessor to a Matkins Johnson digitally tuned receiver was designed and constructed. The existing ATAC computer program was modified.

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LIST OF ABBREVIATIONS

A/D Aralog to Digital

ASCII American Standard Code for

Information Interchange

Baud Bits per second

D/A Digital to Analog

high ITL logic 1 (+5v)

I/O Input and/or Putput

IC Integrated Circuit

IF Intermediate Frequency

ISP Intermediate Sidehand

low TTL logic 0 (Av)

LSB Lower Sideband

TTL Transistor Transistor Logic

USB Upper Sideband

PFC Beat Frequency Oscillator



ACKNOWLEDGEMENTS

I would like to express my deep appreciation to Carole Hickey who wrote the initial ATAC programs. Without her Main System the programming that I did would have been unbearable. I would also like to thank the following people who have helped along the way: LT. Al May, Al Gilkes, Gred Ramos, LI. Bill Hickey, Bop Glaz, Dave Plonden, Dean hayes, and Virginia Mard. Most importantly, I want to thank my wife, Cathy, for all the encouragement and advice she has given me during the writing of this thesis.



T. INTRODUCTION

For many decades man has breamed of the day when machines could relieve him of much of his work. In this era of computers and advanced technology, this dream is now becoming a reality. Connecting computers to other machines, however, is not just a simple matter of running a wire from one to the other. In order for the computer to be able to use its "thinking" ability, it must have some way to translate its signals into a form that is recognized by the machine it is controlling. This is where the interface becomes all important.

An interface is a piece of equipment claced in the data path between two devices. Its number is to rearrange, translate, or change the speed of this data to meet the needs of one or both devices. In other cases the interface is used to convert data from an analog to digital (A/D) or digital to analog (P/A) form, or both. Interfaces of either type range in complexity from a few integrated circuits to the use of microprocessors. Most, however, fall in between. This thesis discusses the design and construction of an interface in this middle class. Here, the computers are the Applied Technology Airborne Computer (ATAC) minicomputer and the MOS Technology Inc.'s KIM-1 microprocessor. Their goal is to program and process outputs from a digitally funable watkins Johnson MJ-8888.

The two computer systems arrive at their goal by



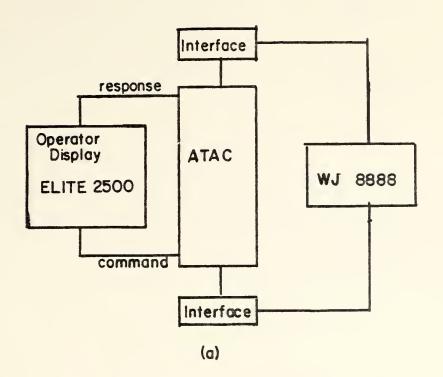
different means. The ATAC uses a closed loop with the operator (Figure 1a) while the KIM-1 excludes the operator while executing its program (Figure 1b). In the ATAC loop the operator actively controls all communication between the computer and receiver. In this way it is possible to display information from the receiver on the video display at any time except during a scan (see Chanter V). It also provides quick reference to the data to be sent, the data last sent, and latest received data. This was invaluable during depudding, from the terminal it is also possible to adjust available canameters as necessary to meet any requirement.

The KTM=1 does not directly exchange digital words with the receiver, but rather exchanges digital data for analog data. This does not provide a feedback loop that includes the operator. Once heads, the KIM=1 program selects and sends data words to the receiver and processes the analog data received until the program comes to an end or is halted by the operator. Direct information is not available to determine when or if a digital word has been sent or received correctly.



Problems encountered during the design and construction of the interface and their solutions are shown in Table I. In this instance signal level compatability was not a problem because the I/O from the receiver, the interface, and the two computers were all TTL logic levels and, therefore, matched. It is believed that these problems are a typical list that may be encountered when interfacing.





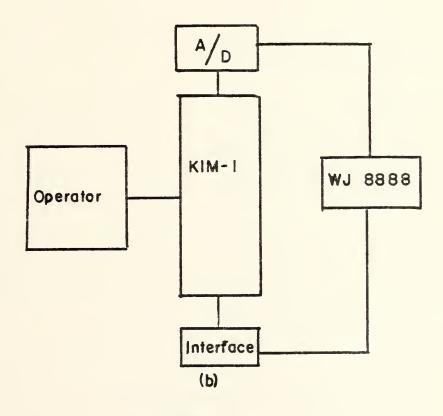


Figure 1 Computer Control



- 1. Noise on the ATAC I/O lines.
- 1. Use of Schottky circuits reduced or eliminated the noise.
- of the computers and the receiver, and different data word lengths.
- 2. Different clock rates 2. ATAC; converted parallel outputs into serial form. KIM-1; used interrupt lines to slave the KIM-1 to the receiver's clock.
- 3. Timira

- 3. Identified receiver periods by the Monitor Clock output. This provided a pulse which signaled stable data.
- 4. Inputting data to the ATAC.
- 4. Open collector buffers were used to sink the required current for proper data transfer.
- 5. Switching between the ATAC and the KIM-1.
- 5. Multiplexers and buffers were used to switch between the two computers.

Table I Problems and Solutions



II. THE RECEIVER

The Markins Johnson WJ-8888 (WJ) is an HF receiver designed for use in the 550 KHz to 30 MHz band. Its advantages include the ability to detect and output both the AM and FM IF signals while simultaneously maintaining a separate output of eight selectable detection modes. Aptions available to the operator include different IF bandwidths, variable RF gain, squelch control, and a tuneable BFO frequency. The WJ is digitally controlled and uses a 64-bit word as shown in Figure 2. This word contains the information necessary to transfer the frequency, detection mode, IF bandwith, RF gain, RFO trequency, and signal strength both internally and externally.

All inputs and outputs from the receiver are controlled by the synchronous, remote T/O hoard. This board is a dated transfer point for all didital data exchanged with the receiver. A number of control lines are needed to provide the necessary demands on the receiver. Three balanced input pairs and four halanced output line pairs, plus a ground are provided for this purpose. All three inputs are required for remote operation. They are address (or enable), tridger, and data input. The address pair is the most important for it serves as the raster "on=off" switch for the remainder of the I/O pairs. The putputs furnish the required clocks (command and monitor), output data, and a local/remote status.



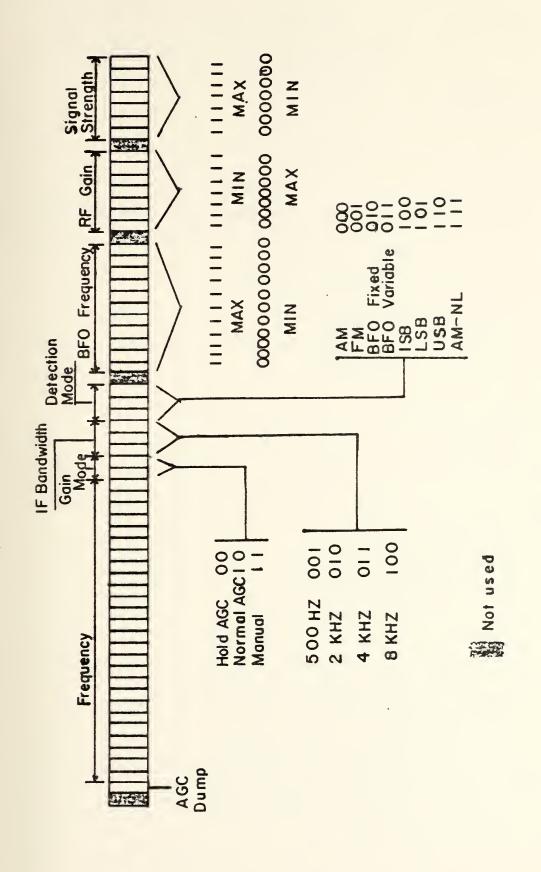


Figure 2 Receiver's Word



The watkins Johnson operates on a sequential cycle divided into four equal periods and six identifiable modes. The periods regulate the different operations while the modes ascertain the origin of the data. Table II shows the interaction of the periods and modes of the receiver. Three of the six modes are memory read and write functions; these cannot be remotely controlled and, therefore, are of no concern here. Of the remaining three, two are the remote active and remote passive modes. These allow the introduction of externally generated data and prevent manual intervention during all but one of the four periods. Manual control is available in the remaining mode, local.

In order to manage the data word movement correctly, the receiver utilizes a common bus or data node arrandement as shown in Figure 3. This simplifies operation by forcing all data words to mass through this node in the same direction, recardless of their origin or desired destination. The multiplexer controls the input to the data node. Control of the multiplexer and, therefore, the origin of the data is managed by the internal modes of the receiver. The objective of period one is to load the receiver register. In the local and remote passive modes, the data word is shifted from the front panel redister, through multiplexer and data node, into the receiver register. difference between these two modes is in the action of the data prior to shifting. The local mode updates the data word from the front panel storage registers guring the early



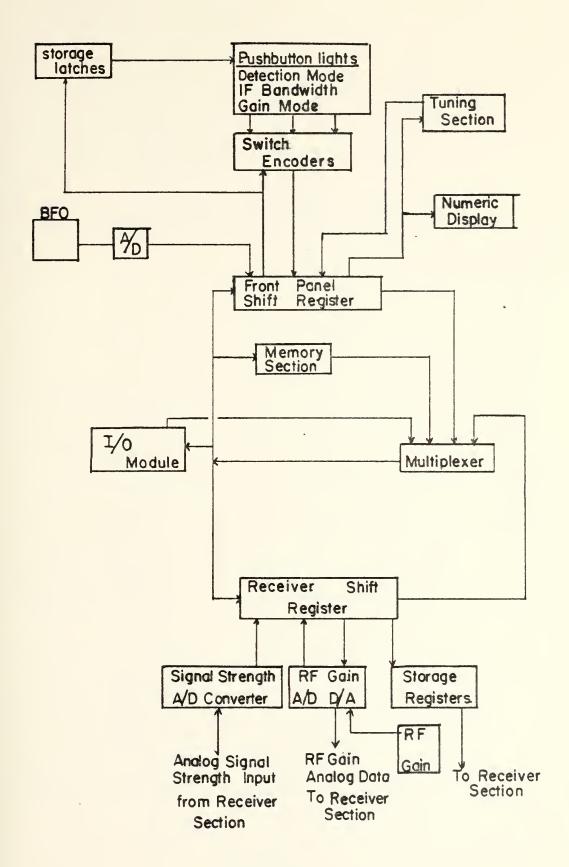


Figure 3
Block Diagram of the Digital Section



7

Local	Load Front Panel	Load Revr Storage		Change to
	Reg from Front	Kea/ Stanl Strength	Display updated	Remote Active or
	Panel/word shifted	and RF gain updated	no words shifted	Remote Passive
	to Receiver	/word shifted to		possible
	Register	FrontPanel Register		
Remote	Word shifted from	Update only Sig Str		Change to Lcl
Passive	FrontPanel Pegister	ZLoad Revr Storage	Same as Local	or Remote Active
	to Receiver	Reg/word shifted		possible
		to FrontPanel keg.		
Remote	Mord shifted from		•	Change to
Active	170 module to	Same as Remote	Same as Local	Remote Passive
	Receiver Register	Passive		automatic.
				Change to
				Local possible

Table II Receiver Modes and Periods



portion of period one. This action is inhibited during the remote passive mode. In the remote active mode the data word organiates from a remote device, is shifted by the command clock through the remote I/O hoard, on to the receiver register via the multiplexer and data node.

The first part of the second period is spent loading the data shifted during period one into the receiver storage registers. During this time the signal strength is updated in the receiver register regardless of the mode. The RF gain A/D-D/A converter functions according to the selected mode. In the local mode the RF gain hits in the data word are replaced by A/D conversion of the front canel RF gain control know. The two nameter modes reverse this action and load the PF gain D/A converter with this data from the word. After this is completed, the word is shifted in all modes out of the receiver register, through the multiplexer and data node, and into the front panel register. If the address line from the remote device is active high, the data word and the monitor clock are available on their respective output line pairs.

Periods three and four inhibit movement of the data word. Period three undates the front panel pushbutton lights and numeric display. Period four is the only period in which changes in receiver mode are allowed. During this period changes from a remote mode to local, or from local directly to remote passive can only be accomplished by depressing the appropriate rushbutton on the front panel. A



change from local and remote passive to remote active is automatically done by the remote I/O board whenever both the address and triager line pairs are active high during this period. The remote active mode immediately reverts to the remote passive mode at the beginning of the next period four. The total cycle time of the receiver is 10.24 msec (2.56 msec period). In order to change modes successfully, it may be necessary either to hold in the pushbutton or to hold the triager and address lines high for up to 7.69 msec (three periods). This ensures that the mode change demand occurs in period four.

All nutrouts are available from connectors J1, and J6 through J10 located on the back of the receiver. J1 is the digital I/O connector. The other connectors are all analog outputs. Jn is a 455 kHz IF signal of at least 20 kHz bandwigth. AM and FM detector monitors are provided at connectors J7 and J9 respectively. JR is a predetection, 455 kHz center frequency IF output whose bandwidth is set by the front panel. A balanced and unbalanced line audio and both upper and lower sideband outputs are available from the appropriate pins at J10. The balanced line operates at all times. The unbalanced line is operable unless headphones are plugged into the front canel. The lower sideband output is active when the receiver is in either ISR or LSB detection modes, and the upper sideband output is active during ISA, USB, and CM modes.



III. THE COMPUTERS

After studying the inputs and outputs from the receiver, three choices were available for further development of the interface. It could be designed to pass the clock pulses on to the interrupt lines of the computer and, therefore, match the computer's timing to that of the receiver. Or, a buffer could be constructed to input the data serially at the clock rate of the computer and output it at the clock rate of the receiver. The third choice, also a buffering arrangement, could exchange data in parallel to the computer and serially to the receiver.

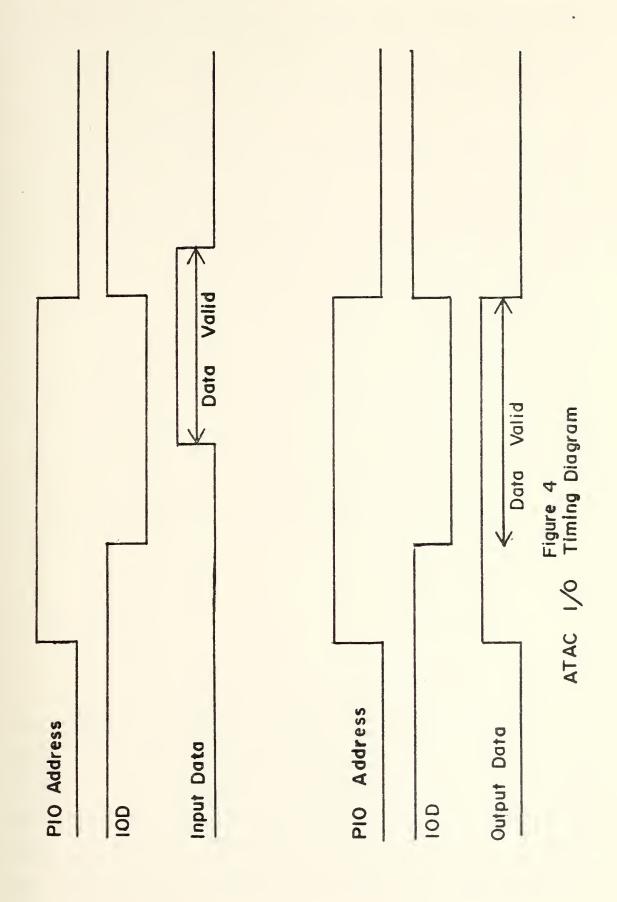
The chief ractor influencing the design decision was the availability and distribution of computer control and I/O lines. For the first computer, the primary objective was to investigate the feasibility of both remotely tuning the receiver and accepting a data word in return. The requirements for the second computer, the MGS Technology Inc. KIM-1, were less strict. Its objective was to tune the receiver digitally through use of the interface. Its input, nowever, was to come from a A/D converter for processing.



A. THE ATAC

The ATAC was originally designed to provide EW service to aircraft. Built to do real-time analysis of signals, it has very short cycle times, optional microcode programming, and double precision arithmetic as part of the standard package. All this, combined with its large instruction set, makes the ATAC a versatile and powerful tool. Although data could be transferred serially by proper programming, the ability of the ATAC to both input and output sixteen bits in parallel on the PIO (parallel input/output) lines proved more advantageous. Any one of the ATAC's sixteen registers can input or output from these lines. In order to properly transfer this data, the PIO bus must be audmented by an address provided by the sixteen bits of the "extended" Arithmetic Register (XAP). Another necessary cutput is one that informs the external device when the ATAC is ready for the transfer. On the ATAC this function is provided by the input/Output Pemand (IOP) line. Referring to the timing diagram in Figure 4, an input command is initiated by placing an address on the XAR lines and following this adoress with a low on the IOD. This signifies that the ATAC register is ready for data. After approximately one microsecond, the IOD is placed high and the address is removed. During this microsecond the data for the ATAC must be stable. For an outcut command, the XAP and the PIN lines first present the address and data for output. When they







are stable, the IOD line is set low. The data is then available for about a microsecond, as before. The IOD line is then placed high and the address and data are removed from their respective lines.

For operator interaction a serial ASCII, RS232 I/O port is also available. A Datamedia Elite 2500 television terminal is connected here to provide the operator with the necessary control and programming capablity for use of the ATAC. By proper programming and use of the XAR lines, it was possible to translate each command for the interface. Using a gemultiplexer on the interface board, four of the five available XAP addresses were separated into sixteen separate commands. One of the remaining lines and the IOD line were used as stropes to identify the neceiver and to signify stable data (Chapter III). This arrangement provided both the adequate isolation and flexible operation desired.

B. THE KIM-1

The KIM-1 is at the other end of the computer spectrum with respect to the ATAC. It is a microprocessor designed around the MOS Technology Inc. series MCSo500 Central Processor Unit. Complete on a single printed circuit board, the KIM-1 is simple to operate and easy to program. While its cycle time is slower than that of the ATAC, it is still much faster than the receiver and more than adequate to meet



analog data supplied from the receiver's FM IF output (J9) and an external A/D converter, the design for this portion of the interface was simpler.

For a more detailed discussion of the KIM-1, its objectives, programs, and operating procedures, see <u>Signal Acquisition</u> and <u>Sampling Using a Microprocessor</u>, by LT. D. Rosenberger.



The interface was initially designed solely for the ATAC. A means of converting four ATAC words into one receiver word was needed first, in order to test the program, the computer, and the receiver together. The simplest and cheanest way to accomplish this conversion and still fully utilize the capabilities of the ATAC was to build a b4-bit register using eight parallel-in, serial-out, eight-bit shift registers. A control section was also necessary to orderly handle this data. The ATAC XAP adgresses were decored by this central section to provide the load commands for the registers and to signal the neceiver to input the word.

The next step in construction was also simple in theory. Since the computer uses the PIO lines for input as well as output, what was needed was a connection which would not interfer with the section already built. The ICs chosen to isolate the two sections are called Tri-State. These ICs have a "no cutout" state in addition to the normal high and low of TTL circuits. They could not, nowever, sink or supply enough current to drive the computer PIO bus. A solution was found by following these ICs with open collector buffers. For only did they provide the necessary amplification, they did not degrade the isolation performance of the Tri-States. This second section also had



a 64-bit register built from the smaller shift registers. In this case, though, they were serial-in, parallel-out. In order to remove the word from the register in sixteen-bit sections, the outputs from the shift registers were connected to four-to-one multiplexers. These multiplexers were Tri-State. With the proper control it was nossible to shift the word from the receiver into this register, and transfer it to the PIO bus in the correct sequence.

Increased complexity in the control section came with this implementation. A method was needed to prevent the computer from transferring a word until it had been completely shifted into the register. The period two clock output from the receiver was used as a reference to provide a pulse to inform the computer when shifting was complete. This pulse was positioned in the same time interval as period three of the receiver. The additional benefit of identifying period four was obtained. This meant that the output for the trigger line to the receiver could be shorter and still meet the requirement to occur in a portion of period four.

After completion of the testing for the ATAC, an interface was designed and constructed for the KIM-1. This design was very simple to implement, since all the necessary timing circuits were already huilt and tested. The two computers were kent from interferring with each other by installation of a manual switch. This switch controls the



address of a multiplexer that separates the lines in the interface common to both computers. The control section was wire-wrapped rather than riaced on a printed circuit board to provide greater flexibility, easier maintenance, and to reduce cost.

A. THE CONTROL SECTION

The heart of the interface is the control section (Figures 5 and 6). The main purpose of this section is to decode and route commands from the ATAC and provide the necessary circuits to interface with the receiver. It also contains the circuits for the operation of the receiver by the KIM-1. The receiver's outputs are driven by line drivers which provide complementary ITL levels. The inputs are applied to line receivers which accept these complementary ITL levels. The interface, therefore, had to use these same receivers and drivers to be compatable with the Matkins Johnson.

The SPST switch rounted on the front of the interface case selects the computer controlling the receiver. With the switch in the ATAC position, a high is placed on pin 1 of IC-JJ and pins 1 and 10 of IC-MM. IC-JJ is now set up to transfer the following: the address and data outputs to the line drivers on IC-LL, the trigger command to pin 2 of IC-Z, and a low in line CCK7. The CCK7 line completes the



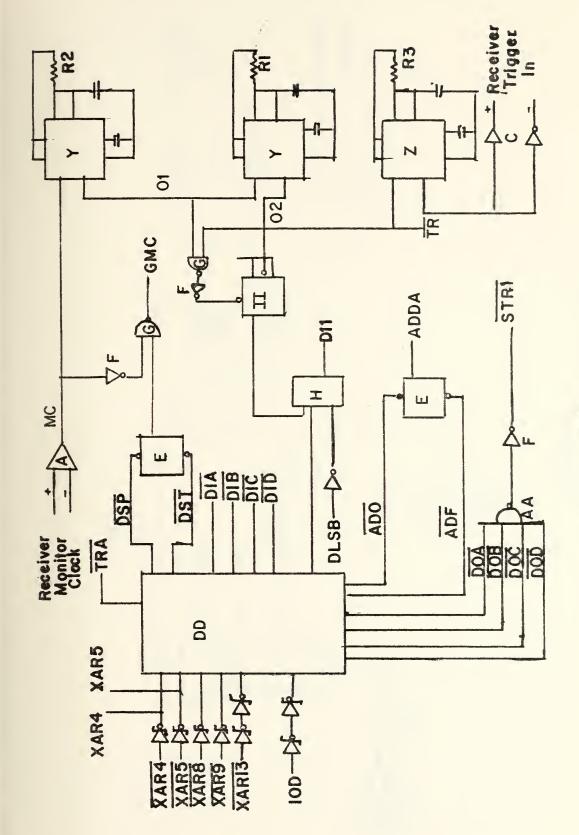
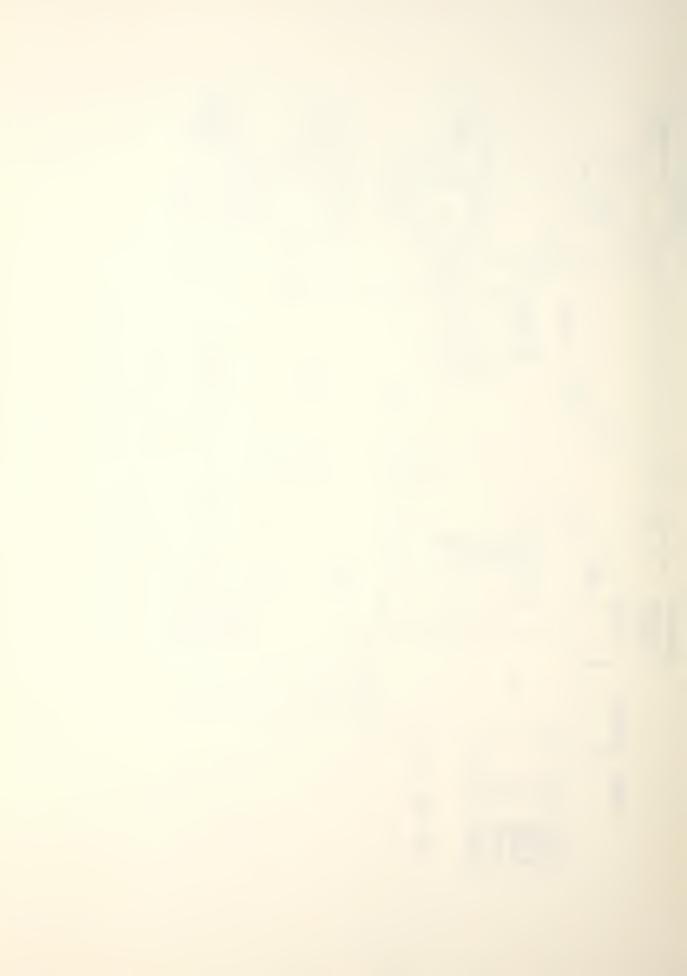


Figure 5 Interface Control Section (Part 1)



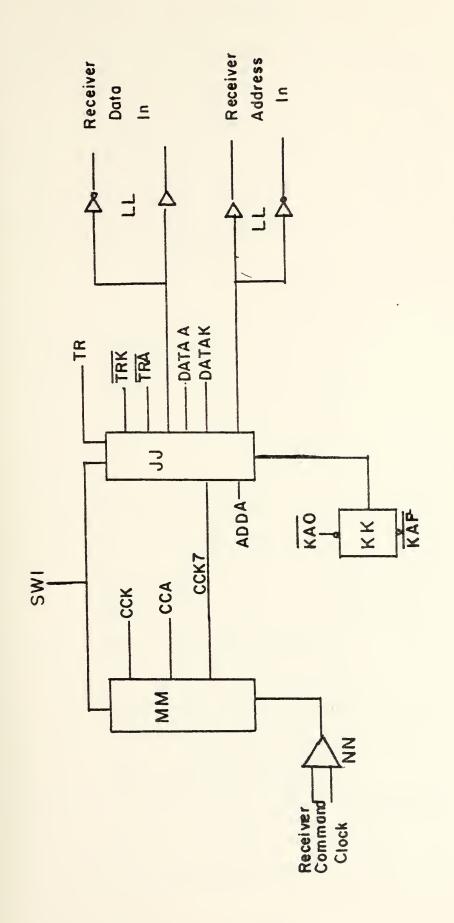


Figure 6 Interface Control Section (Part 2)



```
TRA
      [0]
            AFAC Frieger Commmand
DIA
      [17
            Receiver input word one
      [2]
DIB
            Peceiver input word two
DIC
      [31
            Peceiver input word three
DID
      [4]
            Receiver input word four
DSP
      [5]
            Stop Monitor Clock
            Start Monitor Clock
DST
      [0]
400
      [7]
            ATAC - Address on
DOA
      [8]
            Receiver output word one
DOR
      [9]
            Peceiver output word two
DOR
      [9]
            Peceiver output word two
DOC
     [101
            Receiver output word three
DUD
     [11]
            Peceiver output word four
PDY
     [12]
            Read ull for ready signal
ADF
     [15]
            ATCC - Adoress off
TR
            Peceiver tridger
CCK
            Kin-1 Command Clack
CCK7
            Control Line for Kim-1 Command Clock
CCA
            Command Clock for ATAC interface
ADDA
            ATAL - Receiver Address
KADD
            KIM-1 - Peceiver Address
KAO
            KIM-1 - Peceiver Address On
KAF
            KI'-1 - Receiver Address Off
TRK
            KIM-1 Trigger Command
(Numbers in brackets refer to ATAC XAR commands)
```

Table III

Interface Command List



commands to IC-MM. This IC is a guad Tri-State buffer which is used to control the destination of the command clock. The switch opens buffer one which directs the command clock to the ATAC. The CCK7 line closes buffers two and four disabling the command clock input to the KIM-1.

The ATAC supplies the control section with six lines. Five of these are the XAR pits 4,5,8,9, and 13. Using 4, 5, 8, and 9 as address lines to pins 20-23 of IC-DD, a four-to-sixteen demultiplexer, sixteen (2^4) unique commands (Table III) were made available. The sixth line, the IOD, and XAR 13 were used as stropes or enables for the demultiplexer. In this way YAP 13 was able to specify this receiver uniquely, and the IOD ensured that addresses and data were stable before passing a command. When toth IOD and XAR 13 are low, IC-DD is operational and the output corresponding to the address on pins 20-23 is forced low. At any time that either or both the two strope lines are nigh, all outputs of IC-DD are held high and no commands are generated, regardless of the activity or pins 20-23.

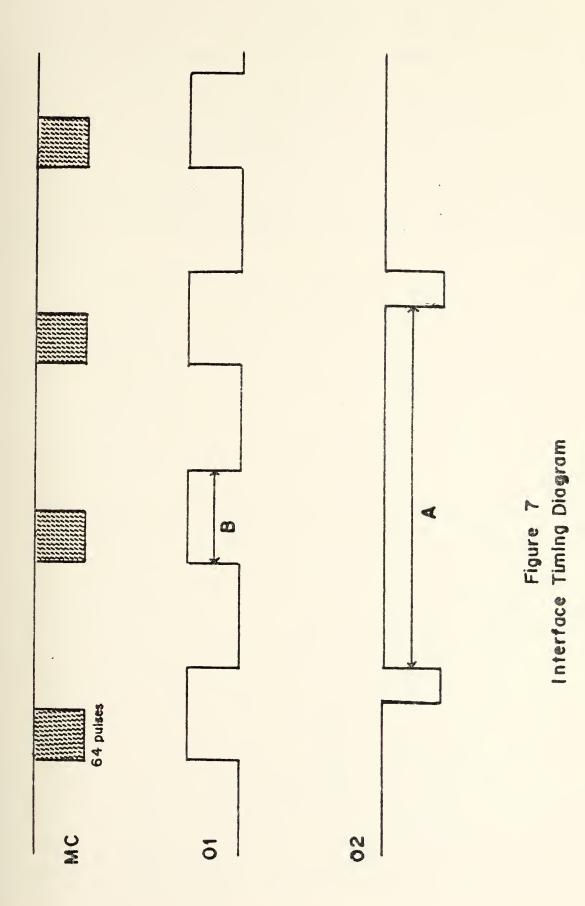
At the beginning of the Receiver Control program (Chapter IV), the ATAC sends commands to address the receiver (ADA) and to open the date for the monitor clock (DST). ADO places a low on bin 2 of IC-E, setting the flip-floo and forcing the ADDA line high. This line activates the receiver's I/A through ICs -JJ, -A, -B, -C, and -LL, as described above. The DST command is passed to



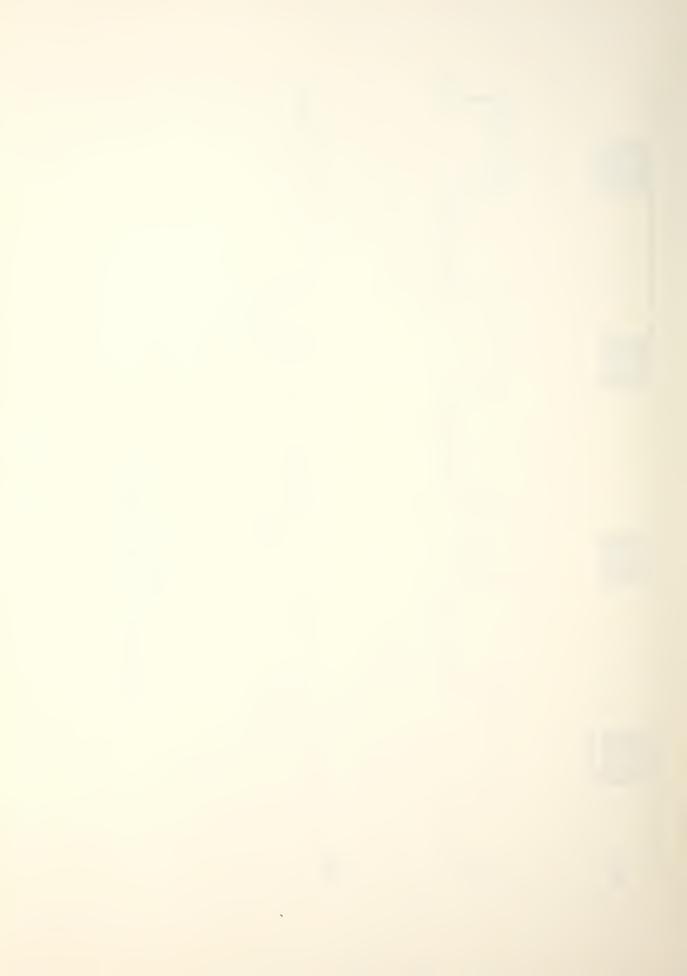
pin 7 of TC-E. This sets this flip-flop and allows the monitor clock (MC) to shift data from the receiver into the storage register during every period two of the receiver's cycle. The MC line is also connected directly to a timing circuit. This circuit produces the pulse described in the early part of this chapter. The first of a monostable multiviprators, IC-Y (Figure 5) is triggered by the first clock culse of MC. IC-Y outputs a pulse, interval A of timing diagram (Figure 7), which triggers the second. The second's output, interval P, is connected to pin 1 of IC-II, a negative-ende triangered, J-k flip-flop. This IC is wired so that it is set on the output of the second multivibrator and reset by either the the output of the first multiviorator or the command IR. The output of this flin-flop, pin 15, is called the PLP. This line is multiplexed with the least significant bit of the output register and inverted by IC-H for use by the ATAC on line D11.

The RLP pulse is adjustable through variable resistors (trimmers) one and two. Trimmer one controls interval B and trimmer two intérval A. In effect, trimmer two varies the position of the pulse and trimmer one its width. The placement and width are the key to proper operation of the interface. The pulse must remain in period three. Although some overlap into period four is allowable it is not desirable, and any overlap into period two could cause





5



incorrect operation. At present, the RLP pulse is programmed for every other period three. This allows the receiver to stabilize between samples taken by the computer. If more or less time is desired, the pulse can be set in every, every other, or every third period three by varying trimmer one. Greater time between pulses can be achieved by changing the .47 uF capacitor (hH=7,8) to one of larger value.

when the ATAC is ready to send a word, it loads the input register of the interface using commands DIA, DIB, DIC, DID, and then waits for a high on the D11 line. When RLP is low, P11 is high and the ATAC sends command TRA. This command is routed to a separate monostable multivibrator, IC-Z, by wav of multiplexer IC-JJ. The timing circuit provides the trigger bulse in period four which changes the receiver's mode to remote active. It also sets PLP high to prevent any interaction with the ATAC until this cycle of the receiver is complete. During the following period one, the receiver sends the command clock to the input register via ICs -JJ and -MM, and inputs the data word through ICs - JJ and -LL. Meanwhile, the ATAC is waiting for PLP to go low again. When it does, the ATAC closes the MC gate win a DSP command and loads four sixteen-bit words with commands DAA, DAB, DOC, and DAD. Once the receiver word is stored in the ATAC, a DSIA command is sent to open the MC date. When the operator has finished excution of the Receiver Control ornaram and exits, the ATAC



sends the interface commands ADF and DSP to turn off the address line to the receiver and close the MC date. The interface is now back in a stand-by status.

In order to set up the interface for operation with the KIM-1, the reset button must be bushed and the computer switch placed in the KIM-1 position. The reset button is unique to KIM-1 interface operation, and is necessary because of the use of the MIM-1's non-maskable interrupt. This interrupt is used to synchronize the KIM-1 with the receiver's command clock. Pressing the reset button places a momentary low on him 3 of IC-rK, the flip-flop that controls the receiver's address line from the KIM-1. This resets the flip-tlop and insures that the command clock output is disabled until required. ICs -JJ and -MM now transfer data from the MIM-1 and nor the ATAC. The CCK7 line follows the address line from IU KK and gates the command clock off and or at the proper time. When the KIM-1 is ready to send a word to the receiver, it waits for a low on the RLP line. This line is connected to the maskable interrupt line. This low generates an interrupt and places the KIM-1 in the output program. This routine provides a trigger bulse for the trigger timing circuit and outputs the data synchronously with the command clock. The difference between the ATAC and KIM-1 actions of the interface is due to the position of the switch. The only function the interface serves is to provide reliable and compatible data to the appropriate device, whether it is receiver or



computer.

. INPUT/OUTPUT REGISTERS

These two registers are used for the ATAC only. The registers were designated input or output by their related function with the receiver. They were constructed to provide the necessary, temporary storage while conventing parallel and serial data back and forth. Both registers are connected to the PTO ous, with the major difference being the Ini+State connections of the serial to parallel, or output register.

The input register (Figure 8) was the easier to implement. It consists of eight d-bit shift registers with parallel input and serial putput. The parallel input comes from the ATAC's PIO bus, which is buffered by schottky inverters to reduce noise. The lines are connected to the ICs in such a way as to load words into two adjacent snift registers simultaneously. This is possible because the shift registers will only latch gata in when their respective load line is low. By proper connection of the DIA-DID lines to pin 1 of the ICs, and coordinating the commands with the data, the output register can be completely and correctly filled. The command clock from the receiver is connected to pin 15 of each of the elaht realisters. When it is present, clocks the data through the register exiting through pin 16 of IC-VV. From here, it goes through the control section



at IC-MM and on to the receiver.

The output reaister (Figure 9) performs the reverse operation. However, in order to separate it into words that are short enough for the ATAC, the data has to be multiplexed before it can be connected to the PIO bus. The Tri-State multiplexers, ICs -I through +L and -U through -X, and the required buffers, ICs -FE through -GG, were used to prevent interaction with the PIO bus when not in use. The timing here is more critical than in the input register system. Refore the ATAC begins a read cycle from the output register, the clock signal to the register is stopped (DSP). This prevents the ATAC from reading non-stationary data. All the TrimState multiplexers are addressed by connecting XAM pits 4 and 5 to pins 2 and 4 respectively. The commands DCA-DOD are ANDed together (NANDed and inverted) and the output connected to all the multiplexers as strobes at pins 1 and 15. When the ATAC reads a word, the XAR bits select the word and the stroke produces it during the microsecond when the PIC hus is available.



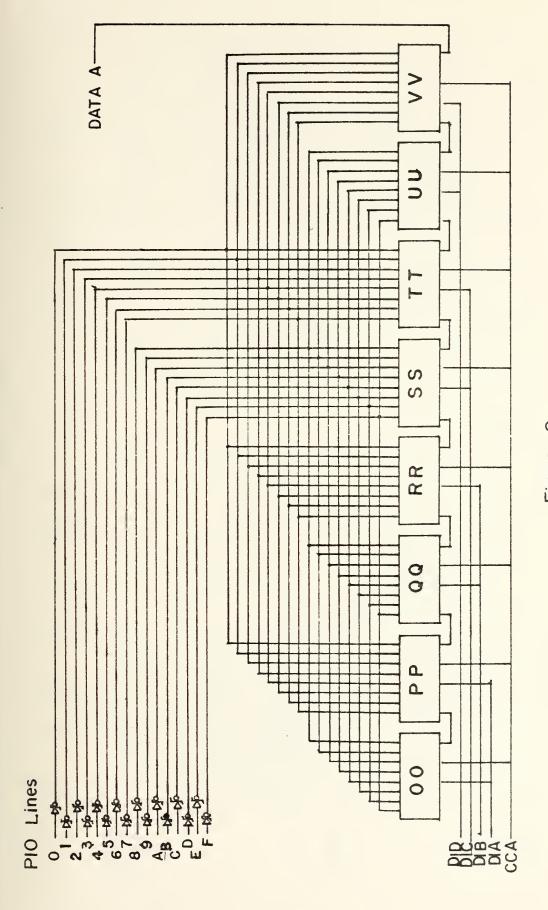
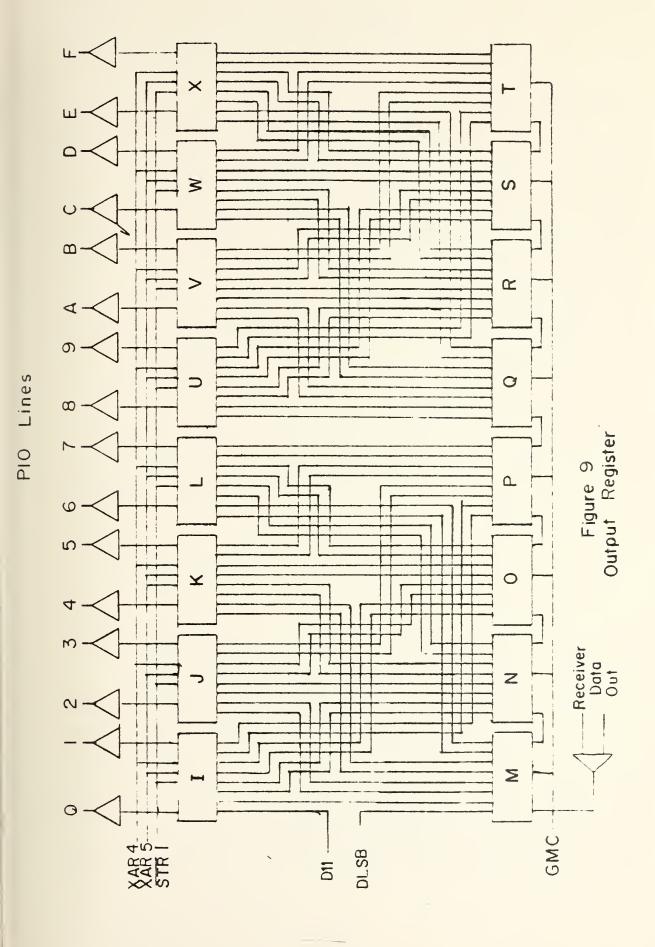


Figure 8 Input Register







V. THE PROGRAM

The ATAC program was written in two major sections; a system monitor and a control. The monitor is called the Main System and provides the operator the ability to program the ATAC from the operator's terminal. Peceiver Control commands the interface and, therefore the receiver. Both programs were initially written prior to the construction of the interface, so many modifications were made using the Wain System and its suproutines. After the interface was built and tested and the Pereiver Control section modified to correctly contol the funing of the receiver, the complete program was saved on paper tage (Appendix C). Uperation of the computer is discussed in Appendix B and a sample run can be found in Appendix E.

A. THE MAIN SYSTEM

The Main System section consists of a small executive and a group of interconnected suproutines (Figure 10). The executive provides a pasis for the subroutines when the receiver control program is not being executed. It is these subroutines that control the input and output to the operator terminal. The input routine is called KEYMR and the output routine, CUIPUI. OUTPUI converts correctly—formatted computer words into ASCII and gisplays them on the



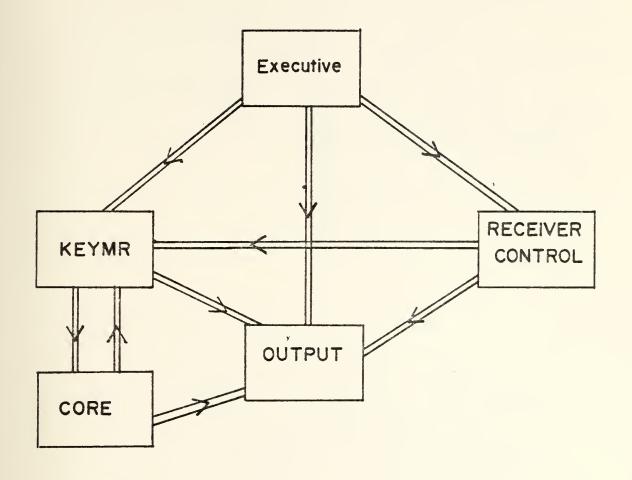




Figure 10
ATAC Program Block Diagram



I. CORE Commands

- CO -- calls CORE from KEYMR.
 - a. DII 'address' -- displays 80 memory locations beginning with 'address'.
 - h. DI 'address' -- displays the contents of memory location 'address'.
 - c. CH 'address' 'value' -- Replaces the contents of memory at 'address' with 'value'.
 - d. CS 'address' -- Beginning at 'address', the contents of memory are replaced with the values typed on the lines following the command.

 Exit is accomplished by command on.
 - e. DO -- Returns execution to CORE if in CS, otherwise returns to calling routine.

II. Peceiver Control Commands

- OJ -- Calls Receiver Control from the executive.
 - a. 0 -- Set-up Routine to input values for entry into Peceiver.
 - b. 1 -- Displays set-up control word.
 - c. 2 -- Displays last control word sent to receiver.
 - d. 3 -- Disclays last control received from receiver.
 - e. 4 -- Sends set-up control word to receiver.
 - f. 5 -- Routine to input scan variables and execute a scan.
 - a. b == Receive and Display control word from the receiver.
 - b. 7 -- Exit program and return to caller.
 - i. b -- Reinitialize program as if entering.

Table IV
AIAC Program Commands



terminal. KEYMP does the reverse, and stores the input in a puffer for use by the caller. KEYMR and OHIPUT were programmed to accept and display only uppercase letters, numerals, and a small number of needed symbols. because of the method employed to convert ASCII to machine code, it was found that each lower case letter entered from the keyboard was automatically mapped into its respective upper case twin. This relieves the operator of the responsibility of using the shift key. A part of the KEYMR, called COPE, is available for use by the operator to display ang/or change sections of memory. The four available commands in this routine and their functions are displayed in Table IV. Care must be taken not to change memory locations which are used by the Main System. This could result in corplete enasure of the ATAC's memory. Without KEYMR, OUTPUT, and COPE, or routines similian to them, it would have been extremely difficult to perform any amount of toubleshooting or modification of the Peceiver Control section.

B. RECEIVER CONTROL

This section of the system is a branch of the executive. Its main objective is to control both outputs and inputs of the interface from the operator's terminal. To assist those operators with little experience in this system, the Receiver Control section is equipped with uncomplicated



instructions and program safeguards. This produces almost foolproof operation but, it does so at the expense of program simplicity. Discussion of this section is separated into two parts. First a broad description of the complete section is discussed, followed by a detailed look at the two suproutines which interact with the interface.

when the Peceiver Control program is entered, if performs five important actions. It initializes all necessary flags; enables the receiver and opens the MC date; sends and receives a complete receiver word; and displays the instruction set to the operator. After this, it calls on NEYMR and waits for a command. Then an input is delivered, the program checks its legality. If it is not a valid command, KEYMR is called again.

A valid command is a numeral between zero and eight (Table IV). These can be separated for discussion into three groups. The display group (0-3) inputs and exchanges information with the operator. The receiver group (4-6) performs operations with the receiver. The final group of commands (7-8) are used to exit or reinitialize the program. Group one has one input and three display commands. Command zero instructs the operator to input the parameters desired. It stores these parameters in memory in the display format, as opposed to control word format. Commands one, two, and three all display carameters. One displays the last parameters set up by command zero. Two displays the last parameters sent to the receiver. Three displays the last



word received from the receiver. Commands seven and eight make up group three. Seven exits the program entirely and returns to the executive after disabling the receiver. Eight, on the other hand, returns the program to its beginning as if it had just been entered.

The remaining three commands are the most important. Group two commands control the actions of the interface. Command four converts the parameters set—up by command zero into control word format. It then calls the I/O suproutine described below, and outputs and inputs a receiver word. To merely receive a word from the receiver, command six is used. The program calls the input subroutine below and then exits to command three to display the parameters received. Command five scans a band of frequencies selected by the operator in search of a specified signal strength. All other parameters remain the same as those set—up by command zero.

with the excention of the instructions executed when entering and exiting Receiver Control, complete control of the interface and the receiver is resident in approximately forty computer instructions. These forty are grouped into the two subroutines WJR and WJS. WJS sends words to the receiver and WJR receives them. WJS loads the information and addresses to be sent to the receiver into the computer registers. The addresses are then matched to a word of data and sent to the interface input register. The routine now waits for the appropriate signal generated by RLP. When



this is received, a tringer command is sent to load the word into the receiver. At this point the routine checks the value of a counter. This test is to prevent the computer entering an infinite loop if either the interface or receiver is not turned on. If the test is unsatisfactory, the routine prints:

IMPINITE LOOP
PLEASE CHECK PERETYER AND INTERFACE

and reverts to operator control. If the test 15 satisfactory, the suproutine automatically continues to WJR. WJm loads another set of addresses into the computer registers. Here, a sport wait for the RLP signal is necessary before any action is taken. The MC gate is closed immediately upon receipt of this signal. The receiver word is then loaded into the ATAC by outputting the address on the XAP lines and reading the data on the PIO lines. When the complete word is received, the MC date is opened. Δt point it is necessary to test for command six. This this determines whether the computer is sending TAST and receiving or only receiving. If the execution of both WJS and NJR is being performed, a comparison between the word sent and the word received is necessary. This comparison is skipped if the computer is only executing WJR (command six). The first three control words sent by WJS and received by NJR are used for this comparison, when it is performed. If



any words differ, the computer returns to WJS to repeat the cycle until one of two conditions are met: either the words match or the WJS counter test discussed earlier fails. If the words match, WJP continues on to convert the received control words into the display format and then returns to the caller.



VI. PECOMMENDATIONS

The system as it stands now is but a beginning. Additions and modifications for future work should include; A/D converters for the receiver outputs; Morse and/or teletype decoders; and an expansion of the computer program. Implementation of either of the first two implies the third. There are some operator assistance program modifications that need to be made. The two that come immediately to mind are (1) a method to abort the scan routine from the orerator's console, and (2) the ability to change individual parameters in addition to the set-up command already located in the organam. Addition of the A/D converters implies a program increase to decode and process this new data. Switching routines and probably some hardware will be needed for the decoders. The capabilities of the system are limited only by the abilities of the operator and programmer.



VII. CONCLUSION

As long as the computer requires only that data obtained from the receiver's word, the interface is flexible enough to provide reliable results. At this time there are no known "buds" in either the interface or the program. Both have been thoroughly tested to provide the operator with the most dependable system cossible.

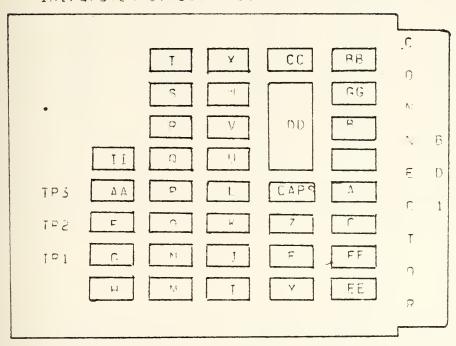


APPENDIX A

INTERFACE WIRING

A. Board 1

Integrated circuit locations (from Top of board).



	!	Ą	!	p	1,	C	1	F	1	F	1	G	1	Н
pir		0588	I	8820	1	8830	1	7476	1	7404	1	7400	\$ 1	74157
1		PD1-M	į	801-K	! {	2-2/2-	3 !	VCC	1	M - 3	1	RD2-E	1	00-14
2	1	D.C.	1	nc	1 8	0-1/0-	3 1	00-8	1	H-3	1	1-9	1	II-14
3	i	801-L	1	9D1-I	: (2-2/6-	41	00-15	1	A-5/Y-8	!	F-11	i	F-2
4	1	nc	1	nc	ŧ	C = 3	1	VCC	1	G = 5	1	E-11	1	I-6
5	1	nc	1	nc	1	801-F	1	VCC	*	ΔΔ-6	1	F-4	1	nc
6	11	F-3/Y-8	1	p = 1	8	601-H	8	VCC	1	G-12	1	F-9	1	nc
7	8	GRD	1	GPD	8	. CDD		DD-7	1	GPO	1	GPD	1	GRD
Д	1	nc	ŧ	nc	1	nc		DD-0	1	T-8	3	nc	1	nc
Q	1	nc	1	nc	1	nc	1	ACC	1	G-6	8	nc	1	nc
10	1	nc	1	nc	1	nc	1	nc	1	II-3	1	nc	1	D.C.
1.1	1	nc	!	nç	1	nc	1	G-4	,	G = 3	1	F-13	1	nc
12	1	nc	1	nc	*	nc	1	VIC	1	1-15	1	F-6	1	nc
13	9	nc	1	nc	1	nc	1	GPD	- [G-11	1	DU-14	8	GRD
14	1	VCC	1	VCC	1	VCC	1	20	1	A C C	1	VCC	1	VCC
15	1	XYXYXXX	1	X X X X X X	< !	$Y \times Y \times Y$	x !	PD1-Y		$\forall\;\chi\;\chi\;\chi\;\chi\;\chi\;\chi$				
16	1	x	!	XXXXX	<1	$Y \times X \times Y \times Y$	χ ;	VCC	8	$X \times X \times X \times X \times X$! .	(XXXXX)		XXXXXX



	; ī	; J		K	L	ivi.	N
pir	1: 7214	7214		7214	7214	74164	74164
1	: X-15	I-15/J	151	J-15/K15	K-15/L15	B-6/M-2	M-13/N-21
2	:0022/J-2	I-5/K.	-2!	J-2/L-2	K-2/U-2	M-1	N-1
3	1 S-3	S-5	!	S-10	S-12	F-1	U-6 !
4	: 0-3	i i i i − 5	- !	$\Omega - 10$	0-12	T-10	U-10
5	1 0-3	0-5	1	0 - 10	0-12	J-6	V-6
6	1 H-4	M-5	1-	M = 1.0	M-12	J-10	V-10
7	1 EE-1	FE-5	!	EF-11	FF-1 !	CRD	GPD :
Д	: GKD	GPO	- !	GRD	GRÚ !	N-A	14-8/0-8
Q	! EE-3	FE-9	1	EF-13	FF-3	VCC	vcc :
1.0	! M = 4	M=0	- 1	M-11	W-13	K-6	W-6
11	0-4	1)-0	!	0-11	0-13	K-10	N-10
12	: 0-4	U-0	1	0-11	9-13	16	X-6
13	9-4	S-0	6	S-11	S-13 !	L-10	X-10
14	10023/J14	K-14/I	141,	1-14/114	K-14/014	VCC	vcc :
15	1F-12/J-1	J-1/h.	- 1 !	K-1/L-1	L-1/U-1	XXXXXXXX	X X X X X X X X
15	: vcc	VCC		VCC	vcc :	XXXXXXXXX	!XXXXXXXX!

	•	Ü	. 0	1	Q	! R		! 5	: т :
pir	;	74164		!		741			
		1-13/0-2	n-13/P-2	!					5-13/1-21
2	-1	0-1	P-1	8	∩ - 1	R-	1	S-1	T-1
3	*	1-5	U-5	!	Ţ - 4	()-	4	! 1-3	U-3 !
4	- !	I - 1 1	U-11	1	T - 1 2	· U -	12	! I-13	U-13
5	1	J-5	V - 1 1	!	J - 4	: V -	4	J-3	V - 3
6		J-11	V-11		J-12	V -	1 >	J-13	V-13
7	1	(13.0)	G⊋D	!	UBD	; GR	Ð	: GRD	GPD :
8	1	11-8/P-8	0-8/0-8	1	P-8/P-8	16-B/	S = 8	R-8/T-8	S-8/F-8
Q	1	VCC	VCC	1	VCC	. vc	C	· VCC	VCC :
10	1	K-2	W-5	!	K – 4	N -	4	K-3	w-3
1.1	1	K-11	N = 1.1	1	K-12	! /, -	12	K - 13 €	W-13 !
12	1	L-5	X − 5	8	L-4	; X =	4	! L-3	x - 3
13	1	L-11	X - 1 1		L-12	X –	12	L-13	x-13
14	1	VCC	VCC	9	VCC	! VC	C	. vcc	VCC :



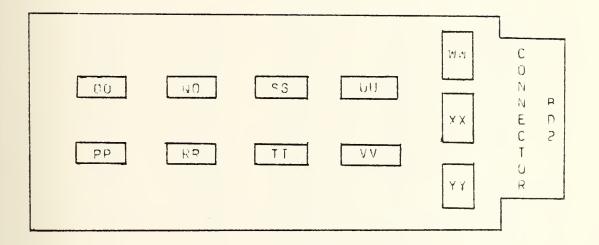
	; U	V ;	:4	Y	Υ	7
pir	1: 7214	7214	7214	7214	556	555
1	IL-15/115	U-15/V15!	V-15/W15	W-15/X15	Y2/Tr-14	GPD :
2	: L-5//-5	U-2/W-2!	V-2/X-2	in - 2	Y-1/HH-6	PD1-E :
3	† T-3	T-5 !	T-10	T-12	HH=5	C-1 !
4	F-3	R-5	P-10	R-12	vcc :	vcc ;
5	P=7	P-5 !	P-10	P=12	BD1C/II1	HH-1 :
6	! M-3	N-5	1-1 0	N-12	Y-9	HH-2/Z-7!
7	1 FF-5	FF-11 :	GG-1	GG-5	GRD :	Z6/Tr-3A!
8	: GPD	GPD !	GKD	GRD	A-6/F-3	VCC :
9	! FF-9	FF-13 !	GG-3	GG-9	Y-6	!XXXXXXXX!
10	↑ N· - /1	N=0	N - 1.1	N-13	. vcc	XXXXXXXX
1.1	₽ = 4	P-0	P-11	P-13	HH-4	*XXXXXXXX
12	! R = 4	P-0 !	P = 1 1	₹-13	Y-13/HH4	*XXXXXXXX
1.3	1 - 4	T-6	T - 1 1	T-13	1712/Tr24	XXXXXXXX
1.4	1L-14/V14	H-14/814	V-14/X14	N-14	VCC :	*
15	11-1/7-1	V-1/N-1!	14-1/X-1	$X - 1 / \{ -1 \}$	XXXXXXX	*
16	1 VCC	Vrc !	4,00	VCC	$X \times X \times Y \times X \times X$	 XXXXXXXXX

	: A A	i ab	! (0 !	ΕŁ	! FF	66 1	HH :	II !
pir	1: 7420	74504	74904	7407	7407	7407	CAPS :	7476 !
1	100-10	CC-6	BD1-17	T-7			Z-5 :	Y-5
2	100-11	100-18	100-23	BD1-1	1BD1-7	PD1-13:	Z-6 :	VCC :
3	inc	BD1-21	nc i	I - 0	L-9	4-9	Y-11:	F-10;
4	DD-9	BR-5	! nc !	901-2	1801-8	RD1-14:	Y-12:	vcc :
5	!DD-13	BR-4	BD1-T	J-7	1 U-7	¥ − 7	Y-3 :	nc :
6	F-5	100-19	P8-1	RD1-3	BD1-9	BD1-15!	nc :	nc i
7	GRD	GPD	; EBD	GRD	: GRD	GPD :	Y-5 !	nc i
8	nc	DD-50	l nc l	BD1-4	BD1-10	BD1-161	GRD	nc i
9	: nc	BD1-20	nc l	J = 9	! U-9	Y-9	GPD :	nc i
1.0	i nc	15-00	no i	RD1-5	18D1-11	nc !	GRD	nc i
1.1	nc	BD1-19	l nc l	K-7	! v = 7	nc i	GRD !	nc :
12	i nc	100-55	nc :	RD1-6	BD1-12	nc :	GRD !	nc :
13	l no	IRD1-18	l nc l	K = 0	! V = 9	nc :	GRD :	GRD :
1.4	1 VCC	VCC	VCC	ACC	: VCC	VCC :	GPD :	H-5 !
15	: XXXXXX	CIXXXXXX	$\{ Y X Y X Y X \}$	\star \times \times \times \times \times	!XYXXX	XXXXXX	XXXXXX	nc :
16	; x x x x x x	XXXXXX X	XXXXXX	XXXXXX	! X X X X X Y	 	X X X X X X }	GRD :



Integrated Circuit

		DD	!
		74154	1
nin		Hoin	!
1	PD1-P	1113	AA-5 !
2	PD1-X	1114	! G-13/H-1!
3	PD1-4	1115	nc !
4	PD1-V	1116	nc i
5	RD1-11	1117	F=3
6	E-8	1118	BP-2
7	E-7	1119	BR-6
8	F-5	1:50	BR-R
9	Δ A - 4	::21	BR-10
1.0	$\Delta \Delta - 1$	1155	BR-12/I-2:
1 1	2-4E	1123	100-2/I-141
12	GRD	1:54	vcc :





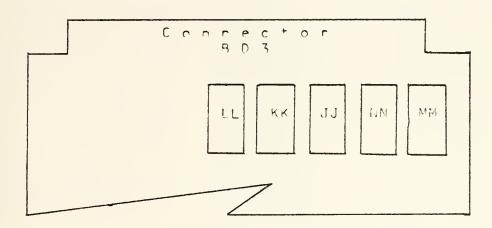
		00	PP	!	D Q	1	RP	!	SS	1	TT	-
pir	1	74165	74165	- !	74165	1	74165	-	74165	1	74165	1
1	ł	PU5-7	BU2-A	*	BD2-8	1	BD2-B	-	BD2-0	-	BD2-C	1
5	-	GRD	GRD	1	GRD	1	GPD	!	GRD	1	GRD	1
3	1	WW-5	YY-0	8	MM - 5	1	Y Y - 0	1	8-WW-2	1	YY-6	1
4	1	NW-12	Y Y - 4	- 1	NW-12	-	Y Y - 4	-	WW-12	1	YY-4	1
5	1	W W - 4	YY-2	1	NN = 0	1	Y Y - 2	!	WW-4	1	YY-2	-
6	1	ww-10	Y Y - 1 0	!	1414-10	-	YY - 10	2	WW - 10	-	YY - 10	1
7	1	nc	nc		nc	-	nc	-	nc	1	nc	-
Д	ļ	GRO	GPD	!	GRD	1	GPD	1	GKD	i i	GRD	1
Q	1	PP-10	0.0-10	1	PP-10	1	53-10	-	TT-10	-	110-10	1
1 0	1	VCC	U() = 6	8	PP-0	1	90-9	!	RR-9	3	55-4	1
1 1	1	X X - 2	X X - 4		< X = 2	-	X X = 4	1	X X = S	-	X X - 4	1
12	1	x X - 1 2	Y X − 0		xx-12	1	X X - 0	1	XX-12	-	X X - P	1
13		114 - 8	8-XY	!	· , v*/ - P	í	5 – X Y		NW-8	1	8-xx	1
14	1 1	W. M 6	Y Y - 1 2	1	V1 M - 6	1	YY-12	-	WW-6	1	YY-12	1
15	1	15-208	602-21	1	BDS-51	-	BD2-21	- !	BD5-51	1	PDS-51	1
16	1	VCC	VCC		VCC	1	100	8 1	VCC	1	VCC	!

	8 7	UU	;	VV	!	NIA	ΥX	;	Y Y	
pir	1	74165	!	74165	!	74504	74504		74304	
1	-	802-0	1	6-5-0	1	802-17	602 - 1	0 :	BD2-4 :	
2	1	GRD	1	GPP	- !	00-3 * ;	00-11	* !	PP-5 * !	
3	1	WW-2	!	Y Y -6	- 1	BD2-15 !	HD2-9		BD2-3 !	
4	1	WW-12	1	L - A A	!	00-5 * :	PP-11	*	PP=4 + !	
5	-	WM = 0	8 1	Y Y - 2		BD2-13	8 - 278	1	802 - 2 :	
6	1	wW-10	!	Y Y - 1 0	!	00-14 *!	PP-12	* }	PP-3 * !	
7		nc	8	20	- 1	GRD !	GRD	!	GRD :	
8	1	GRD	!	CBC	- !	00-13 *!	PP-13	* !	no !	
0	1	V V - 1 0	;	872-K	. !	5D2-12 !	BD2-7	- 1	nc !	
10	1	TT-9		Ut) = G	1	00-6 + 1	nc	1	PP-6 * 1	
1.1	!	X X - 5	!	x × = 4	1	BD3-14 ;	nc	- 1	602 - 5 :	
12	1	x x - 1 2	!	××-6	- 1	00-4 * !	00-12	* !	PP-14 *!	
13	1	VI WI - 8		$X \times - 8$	8	BD2-16	BD2-1	1 1	8D2-6	
1.4	1	W 101 - 6	1	Y Y - 1 2	1	VCC :	VCC	- 1	VCC :	
15	-	BD2-21	1	PD2-21	!	! X Y X Y X X Y X !	XXXXXX	X X 🗜 :	*XXXXXXXX	
16	-	VCC	!	VCC	- !	, x y x y x y x y x 	X X X X X X X	X X 🗜 .	!XXXXXXXXX	

^{* -} bus connection - only first connection shown



C. Board Three Integrated circuit locations (from Ton of board)



Integrated Circuit

										N 1.7	
	1	JJ	1	K.Y.	7	LL		74 JV	i	Niv	i
pir	1	74157	1	7476	1	8830	1	74126	1	0588	-
1		803-1	!	VCC	ILL	-2/J	J - 7 ¦	803-1	1	BD3-5	1
2	1	4K-15	;	BD3-1	1 111	-1/11	3!	5D3-17	1	nc	1
3	1	003-6	160	3-12/	11:05	-2/LL	4!	BP3-16	;	BD3-4	1
4	0 1	LL-10	1	nc	1	LL-	3 !	JJ-12	1	00	
5	1	803-8	!	VCC	4	903-	7 :	GKD	1	nc	1
ó	ŧ	BD3-9	1	nc	!	BD3-	10 :	BD3-16	1	MM = Q	1
7	1	LL-1	!	nc	!	640	1	GRU	3 1	GRD	1
8	1	GRD	1	nc	!	803-	10 !	BD3-2	1	00	1
9	1	5D3-13	1	nc	!	803-	12 !	NN-8	1	nc	1
10	1	BD3-14	1	nc	!LL	11/J	J-4!	BD3-1	1	n c	- 1
11		nc 5	8	nc	111	12/11	10:	Br3-3	!	nc	1
12	1.1	MM13/MM-4	8 T	nc	111	13/11	111	MM + 0	8 1	nc	1
13	1	GRD	1	CBL	!	LL-12	2 !	JJ-12	!	nc	1
14	!	rK-15	1	nc	1	VCC	!	VCC	!	VCC	2
15	1	GRD	! JJ	-2/JJ	14:xx	(XXXX)	XXX!	XXXXXXXXX		(XXXXXXXX)	X ;
16	1	VCC	!	nc	! x x	(XXXX)	XXX E	X		X X X X X X X X X X	x :



D. Connectors Circuit goard Fage-connectors

		0.0.5	
	RD1	BDS	PD3
1	EE-2/902-10/CM1-2		SW1/JJ-1/MM-10
5	EE-4/BD2-11/CN1-3	YY-5/RD1-13	MM-8/BD2-21 :
3	!EF-6/RD2-12/CN1-4!	YY-3/RD1-14	MM-11/CN3-1
4	LEE-8/RD2-13/CN1-5	YY-1/RD1-15	NN-5\CM5-5
5	!EE10/PD2-17/CN1-6!	YY-11/BD1-16	! NN-1/CN2-3 !
6	!EE12/802-16/CN1-7!	YY-13/RD1-12	! JJ-3/8D1-Y !
7	!FF-2/FD2-15/C*1-8!		LL-5/CN2-10
• p	!FF-4/PD2-14/CN1-9!		JJ-5/CN3-2
9	!FF-6/802-9/CN1-10!		JJ-6/802-K
10	!FF-8/8D2-8/CN1-11!		LL-6/CN2-11
11	!FF10/RD2-7/CN1-12!		: KK-2/CN3-3
	!FF12/RD2-6/CN1-13!		1 KK-3/CN3-4
12	, , , , , , , , , , , , , , , , , , , ,		JJ-9/RD1-E
1 3	GG-2/PD2-2/CN1-25		
14	GG-4/202-3/011-24		JJ-10/801-P
15	:GG-6/9UZ-4/CN1-23!		JJ-11/CN3-5
15	GG-8/8D2-5/CN1-22		nc
17	CC-1/CM1-11	Wr -1/PD1-5	rc
1 2	PB-13/CN1-17 !	20	FF-6/CMS-15
10	F8-11/CN1-19	nc	LL-8/0N2-11
5.0	3P-9/CN1-1b	n c	! KK=3/PESET !
21	BP-3/CN1-20 :	00-15/803-2	l no l
55	i nc	ERD	! VCC !
Δ	GRD !	00-1/BD1-x	: GRD :
Ë	i nc	GG-1/PD1-W	i nc
C	: II-14/CN3-6	SS-1/PD1-V	nc !
D	i nc	UU-1/PD1-1	i no
Ε	: 7-2/PD3-13 :	nc	i nc
F	C-5/CN2-9	nc	nc
Н	: C-6/CN2-8 :	nc	nc
J	8-3/01/2-7	nc	nc
K	B-1/CN2-6	nc	nc l
L	A-3/CN2-5	nc	nc
V	A-1/CN2-4	nc	nc
M	l nc	nc	nc
P	DD-1/PD3-14	nc	nc
R	nc	nc	l nc
S	nc	nc	nc
T	CC-5/CN1-14		
Ú	00-5/802-0	nc	nc
V	DD-4/6P2-6	nc	nc
V Vi	1 DD-3/8D2-B !	nc	nc
X	D0-2/802-A !	n c	nc
		nc	nc
Y	E-15/b03-6	nc	nc
7	· vcc :	u c	nc



Cabinet Connectors

```
CM1 !
pin!
                         C 1/15
                                          CN3
                      GPD
                                    1 BD3-3 "CCK" !
1 !
 2 !
      BD1-1 "P10 0"! BD3-4 "CC - " ! BD3-8 "DATA K"
 3 !
      BD1-2 "PIO 1"! BD3-5 "CC + " ! BD3-11 "KAG"
      BD1-3 "PIO 2"! PD1-M "MC - "
                                    ! PD3-12 "KAF"
4 !
 5 !
     BD1-4 "PIO 3"! BD1-L "MC + " ! BD3-15 "TRK"
                                    | PD1-3 "PLD"
  ! BD1-5 "PIO 4"! PD1-K "DO - "
 7 !
    BD1-6 "PIO 5"; PD1-J "OO + "
                                           nc
 8
      bD1-7 "PIC 6"! RD1-H "IR -
                                           nc
    BD1-8 "PIO 7"! BD1-F "TR +
9 !
                                           nc
10 : BD1-9 "PIN A"! BD3-7 "DI -
                                           nc
11 : 8D1-10 "PIO 9":8D3-10 "DT + "
                                           nc
12 |BD1-11 "PTO 10" |BD3-19 "AD - "
                                           nc
13 :8D1-12 "PTG 11":6D3-19 "AD + "
                                           nc
14 : Br1-T "Inu" :
                                          GRD
                         nc
15 !
      nc
                         20
                                           nc
16 | B01-17 "YAR 4"!
                         nc
                                           nc
17 ! PD'1-18 "XAP 5"!
                         r \in C
                                           nc
18 ! BU1-20 "YAR 9";
                         n C
                                           O.C.
19 ! BD1-19 "YAR 9";
                         nc
                                           nc
20 1601-21 "XAR 13"!
                         nc
                                           \cap \subset
21 ! nc
                         n c
                                           nc
22 !BD1-16 "PTO-15"!
                         n c
                                           nc
23 !BD1-15 "PIO-14"!
                         n c
                                           nc
24 |BD1-14 "PT0-13"!
                         nc
                                           nc
25 | BD1-13 "PT0-12"!
                         nc
                                           nç
```

E. Discrete Components

Capacitors Resistors

.01	uF	;	HH-1/HH-14	1					l r i.mme	٦ ج		
. 2	uЕ	;	HH-2/HH-13	1			1		5		3	
.20	uF	-	HH-3/HH-12	9	Δ	- 1	Y - 1	1	Y-13	-	2-7	1
.01	uF	-	HH-4/HH-11		В	1	VCC	1	VCC	1	VCC	1
. 01	uF	1	HH-5/PH-10	1	С	1	VCC	1	A C C	-	VCC	1
1.7	F	- 1	HH-7/HH-8	1								



APPENDIX B ATAC OPERATING INSTRUCTIONS

```
Power Up
    Turn on front panel power then turn on power supplies.
Power Down
    'Halt'
    'Master Clear'
    Power off to sucolies, power off to control
   panel.
Run Program
    'Master Clear'
    vial 'IMR'
    'AUX PEG!
    'FNTER' (associated with AUX REG)
    ' ME MORY!
    Set start address +1 in keyboard (Hexadecimal)
    IPCD!
    'ENTER' (associated with PCP)
    PUNI
Stop a Program
    'HALT'
Read Memory (from front panel)
    'HALT'
    Set desired address in key board
    Select 'MAR'
    'FNTER' (associated with MAP)
    'INC' (increment)
    'DEC' (decrement)
    Address is displayed above MAP key, data is displayed in
        red LEDs above MEMORY key.
    Use IMC or DEC as necessary to arrive at memory location
        desired.
Write into Memory (from front panel)
    "HALT!
    Set address desired as described in Read Memory.
    Set desired data into keyboard
    'ENTEP' (associated with MEMORY)
    Value in keypoard will be entered into either Memory
        (MEMOPY) or A computer Peaister (FILE).
```



```
Bootstrap Load (paper tabe)
'HALT'
'MASTER CLEAR'
'AUX REG'
Dial 'IMR'
'ENTER' (associated with AUX REG)
'MEMORY'
Set 0001 in keyboard
(0001 = Load, 0002 = Verify only)
'RUN'
At end of tabe check program status lights (red LEDs below PCR and MAK pushbuttons)
```

0000 = Load good
FFFE = Parity error
FFFT = Verify error



APPENDIX C ATAC PROGRAM ASSEMBLY

Assembly of a program is divided into five parts; writing, producing absolute deck on IRM 360, conversion of absolute deck into ATAC format, nunching paper tape, and loading ATAC.

A. Mriting the program.

Programs for the ATAC must be written in the assembly language described in ATAC manuals Volumes One, and Eight. The finished program must be placed on cards for the IBM 360 in the following format:

B. Producing an absolute deck

The first step is to load the assembler on to the IBM 360 from magnetic tare. This is done by executing program A in Appendix E. This transfers the program from tape to disk and saves it for one year. Once the assembler is stored the



following cards placed in the front of a program written following the instructions in I above will produce an absolute deck and a print-out of the program.

```
//ATACASSM JOB (0729,0194,0052), CCH ATAC ASSEM, ', TIME=1
//ASSEM
          EXEC PGM=APSS, REGION=220K
//STEPLIE DD USN=S0729.ATAC.ONF, UNIT=3330,
                 VOL=SEP=DISK02, DISP=SHP
11
//FT06F001 DD
                SYSCUT=A
                SYSCUT=P
//FT07F001 DD
//FI05F001 DD
                DDNAMESYSIN
//FT08F001 PD
                UNIT=SYSDA, SPACF=(CYL, 1)
                UNIT=SYSDA, SPACE=(CYL, (7,2)),
//FT09F001 DD
               DCB=(RECFM=VBS,BLKSI7E=7180,LRFCL=92)
11
                UNITESYSUA, SPACF=(CYL, (7,2)),
//FT10F001 DD
                DCB=(RFCFM=VPS, P1 KSIZE=4204, LRECL=42)
11
                UNITERYRDA, SPACE = (CYL, (7,2)),
//FT20F001 DD
                DCR=(RFCFM=VRS, dLKSI7E=2004, LPECL=500)
11
//SYSPPINT DD
                SYSPUT=4
//SYSTN
           DD
$J08
SASSEM
         IDT
               ATAC
(place written program here.)
         END
BBASE
         D
SLOAD
5END
```

The absolute deck is in the form:

0500169c0009adbc3109bc9c3109c8bc7109c09c7109d8b60309bbd932/ /e10100009c015a 05101609f49c0109f6ed0008aee1010a02ed000230e10109f7ed0007ae/ /c1070509201258

which must be translated for the ATAC. The memory location of the first word is located in the first four columns.



Columns five and six contain the number of word fields on the card. The assembled program is located in columns 7 - 70. The remaining two columns are parity.

C. Conversion

The absolute deck received from the IRM 360 is loaded into the PDP=11. After the data from the cards is checked, the conversion program (convert 'filename' 'filename') can be executed. (Program C in Appendix F)

D. Punching Paper Tape

This code must then be transferred to the PDP=11 (A) where a paper tape can be punched. Here, the command to punch a tape is:

cat 'filename' >/dev/ptp

E. Loading the ATAC

In order to load a tape the RS232 connector must be connected to the Paper Tape reader and the reader set to 1200 haud. The tape is loaded by following the instructions in Appendix B.



APPENDIX D

SAMPLE ATAC OUTPUT

Operator inputs are underlined.

4=ENIFR TENTATIVE

5=SCAN

•	
Operator Display	*Comments
EXEC +JDKDKJFJjjnmun JDKDKJFJJJNMUH	*Executive echos *entries other than *commands
EXEC + <u>CO</u>	*Entry into CORE
CORE +CH 0F00 0900 0F00 0900	*Location OFOO *changed to 0900
CORE +DI 0F00 0F00 0900	
CORE +CS 0F00 +0256	*Locations 0F00 to 0F03 *changed
+ <u>0123</u> + <u>4567</u>	
+ <u>DO</u> 0F00 0256 0F01 0123 0F02 4567	*completion of change
CORE + <u>DO</u>	*Fxit from CORE
+MJ U=SET-UP 1=DISPLAY IFNTATIVE 2=DISPLAY CONTROL 3=DISPLAY RECFIVED	*Entry into Receiver *Control



6=RECEIVE CONTROL 7=DONF 8=REINITIALIZE

RECEIVER CONTROL +0

FRER (HZ)

+1240000 DETECT MOPE 0=AM 1=FM 2=BFO FIXED 3=BFO VARIABLE 4=ISB 5=USB 6=LSB 7=AN-NL

+0 GAIN MODE U=HOLD AGC 2=NORMAL AGC 3=MANUAL AGC

+0 IF BANDWIDTH 1=500 HZ 2=2 KHZ 3=4 KHZ 4=8 KHZ

+4 RF GAIN (PERCENTAGE)

+88

RECEIVER CONTROL
+1
FREQ = 1240000 HZ
GAIN MODE = HOLD AGC
IF BANDWIDTH = 8 KHZ
DETECT MODE = AM
BFO FREQ = 455000 HZ
RF GAIN = 88%

RECEIVER CONTROL +2



FRED = 550000 HZ

GAIN MODE = HORMAL AGC

IF BANDWIDTH = 8 KHZ

DETECT MODE = AM

BFO FREQUENCY = 455000 HZ

RF GAIN = 85%

RECEIVER CONTROL

+3
FRED = 550000 HZ

GAN MODE = NORMAL AGC

IF BANDWIDTH = 8 KHZ

DETFCT MODE = AM

BFO FREGUENCY = 455000 HZ

RF GAIN = 85%

SIGNAL SIPENGTH = 66%

PECFIVER CONTROL +4

RECFIVER CONTROL +5 SCAN START FRED IN HZ

+1000000 END FREG IN H7

+1008000 FREG INCREMENT IN HZ

+1000 SIGNAL SIRENGTH %

+67
FREQ = 1001000
GAIN MODE = HOLD AGC
IF BANDWIDTH = 8 KHZ
DETECT MODE = AM
BFO FREQUENCY = 455000 HZ
RF GAIN = 88%
SIGNAL SIPENGTH = 72%

RECEIVER CONTROL +7 EYEC +

*Exit from *Receiver Control



APPENDIK E CONVERSION PROGRAMS FOR THE ASSEMBLER

A. This program is run on the IBM=360 to transfer the ATAC assembler from tape ATT=006 to Disk and stores it there for one year.

```
// [GREEN JOB CARD]
//SYSPRINT DD
                SYSOUT=A
//SYSUT1
           DD
                UNIT=SYSDA, SPACF=(TPK, (40),, CONTIG)
            9
                 UNIT=2314, DSN=S0729. ATAC. ONE,
//DA1
11
                SPACE=(TPK, (50,10,10),, CONTIG),
                DISP=(MEN, KEFP), VOL=SEP=SPOOL3
11
//IITAPE DO UNIT=(2400, DEFER), DISP=(NEW, PASS),
                 1 AREL = (3, SL,, IN),
11
11
                DC9=(DFN=2, BLKSIZE=800, LPECL=80, RECFM=FB),
                VUL=SER=ATIOO0
//
1/3YSI
           00
         COPY
                PDS=ATI.APSS.LOADLIB, TO=2314=SPCOL3,
                FROMOD=11TAPE, FROM=2400=(AT1006,3),
                PENAME = S0729. ATAC. ONE
1 *
           EXEC PSM=IENL, REGION=150K,
//BUILD
11
              PARM='DVLY, XPEF, LET, LIST, SIZE=(256K, 20480)'
//SYSPRINT DD SYSCUT=A
//LIBPARY DP DSN=S0729.ATAC.ONE,UNIT=2314,VOL=SER=SPOOL3,
                DISPESHR
11
//SYSLIB DO DSNAME=SYS1.FORTLIB, DISP=SHR
//SYSLMOD DD DSNAME=S0729.ATAC.ONE,
11
                  UNITE 3330, VOL = SER = DISKO2,
                DISP=(NEW, KEEP), LABEL = RETPD=360,
11
11
                SPACE=(CYL, (5,1,2), RLSE)
//SYSUT1 DD UNIT=SYSDA, SPACE=(TPK, (19,19),, CONTIG),
                SEP=SYSLMOD
//GYSLIN
          DD
 INCLUDE LIBRARY (PMIDL)
CHANGE MSIM (THESAPP)
 INCLUDE LIBRARY (APSSMOM)
 INCLUDE LIBRARY (MSIM4, ASEM5, SIM16A, SIMTR1, SIMIO1, GUL)
 INCLUDE LIBRARY (XPEMON)
OVERLAY AT
 TNSEPT SIMUL, *MSIMULA, IHENTRY, IHESAP
 INSERT MINI, IN, OUT
 INSERT IMEDRY, INFXID
```



```
INSERT IHERSM, THECSM
 INSERT IMERSK, IHFIOX, IMETOP, THEDID, IMEDOR
 INSERT IMEDIB, THEDDA, IMETOB
 INSERT IHETOA, THEOCL
 INSERT THERSO, THEBSE
 INSERT IHEJXS
 INSERT THEOSD, THEOST, THERST
 INSERT IMEVPE, IHEDMA, IHEVER
 INSERT IHEDNO, IHEVED, IHEVEA, IHEVED, IHEVER, IHEVSC
 INSERT IHEVSD, THEVFE, THEDON, THEUPB
 INSERT IHEVEC, IHEVPE, IHEVPG, THEVQB, IHEVQC
 INSERT THEADN, THETOO, THETOF, THEPPT, THEVQ4, THESPRI
 INSERT THEREG, THEERR, THEST?
 INSERT MISET
 OVERLAY AT
 INSERT ASSEM, REWIND, REW72, DSKOUT, CARDIN, DISKIM, ERPRI, PRIADD
 INSERT WRDATA, PRICOM, PRINOR, MRITEX, REFTIT, PREF, EPTIT
 OVERLAY AL
 INSERT PARMED, PRESIM
OVERLAY AL
 INSERT SMLTR, GRATHA, STRTSM, TRAGE
 INSERT RDCPD, ABNPMT, ARTHER, TRACE, HGRAM, HGRAMI, HGRAMS
 INSERT IDINIT, ACTIVE, STATIM
 INSERT DEVDIA, ACT, TIME, INT, MAND, DEADT, DEPUG
 OVERLAY 32
 INSERT LEVEL, DMATOI, DMAIDA, DMATOD, RIDIO
 INSERT REMACT, DMA, DMATM, PIO, PIOTM, PIOTMI, INTOLY, DMAINT
 INSERT DIRAN, PHIACT, RANDOM
 OVERLAY AL
 INSERT HGPRNT
 OVERLAY AT
 INSERT LOADER
 OVERLAY AT
 INSERT LINK, ENTEXT, SILH
 OVERLAY AT
 INSEPT PLATAC, TOPACK
OVERLAY SOBJECT (REGION)
 INSERT OPJECT, TWIT, LTB, RCALPH, RCHEX, RCINT
 INSERT MDATE
 OVERLAY SOUMP (REGION)
INSERT SMOUMP, PAGE
ENTRY MAIN
NAME APSS
/*
            FXEC PGM=IE3COPY
11
//SYSPRINT DD
                SYSCUT=A
//SYSUI1
                 DISP=SHP, UNIT=2314, VOL=SEP=SPOOL3,
          DD
11
                DSN=SU729.ATAC.ONE
//SYSUIZ DD DISP=(NFW,PASS),UMIT=3330,VOL=SER=DISK02,
11
             DSN=S0729.ATAC.TNO,
```



```
SPACE=(13030, (61, 0, 14), RLSE),
11
               DCB=(RFCFM=U,BLKSIZE=13030),
11
11
               ,LABFL=RFIPD=360
//SYSUT3
           00
                UNIT=SYSDA, SPACE=(TPK, (20,5))
//SYSUT4
                UNIT=SYSDA, SPACE=(TRK, (20,5))
           DD
//SYSIN
           DD
           COPY OUTDD=SYSUIZ, INDD=SYSUI1
o. This program converts the IRM-360 absolute deck into
correct format for the ATAC.
main (argc, *argv)
   int arac:
   char *arav [];
   (register crctr, index, index;
    int stchr:
    int thory [731;
    struct buffr
      lint floes;
       int nleft;
       char *nexto;
        char *buffs [512];
       } hufin, bufot, *ontr1, *ontr2;
    stchr = 020;
    if (arac != 3)
       {printf ("Calling arguments are incorrect#");
        exit (0);
    bufin.fldes = onen (argv [1], 0);
    if (bufin.flaes < 0)
       {printf ("Cannot open %s#", argv [1]);
        exit (0);
       }
    potr1 = &bufin.fldes;
    bufot.fldes = creat (arov [2], 0777);
    if (bufot fldes < U)
       {printf ("Cannot open %s#", arov [2]);
       exit (0);
       }
    pntr2 = &bufot.fldes;
    putc (stchr, pntr2);
    while (crctr >= 0 &R index <= 72)
        tmory linnex++) = (crctr = getc (pntrl));
    index =- 3;
    index = 0;
    while (index < 4 && index < index)
```



```
putc (tmprv [index++], pntr2);
index = index + 2;
while (crctr >= 0)
   {while (index < index)</pre>
       {if (tmpry [index] == '#')
            index++;
          else
            putc (tmpry [index++], ontr2);
       }
    index = 0;
    while (croth >= 0 88 index <= 72)
      tmpry lindex++) = (crctr = aetc (pntr1));
    index =- 3;
   jndéx = o:
putc (stchr, nntr2);
fflush (pntr2);
close (hufin.flces);
close (hufot.flres);
```

C. The following program executes the program above and converts the nutput into the correct code.

```
atac #1 $2
if ! -r $2 exit
mv $2 temp2
tr "[0*]" "[040*]" <temr2 > temp1
tr "[1+]" "[001+]" <temp1 >temp2
tr "[2*]" "[002*]" <temp1
tr "[3+]" "[043+]" <temp2
tr "[4*]" "[004*]" <temp2 >temp1
tr "[5*]" "[045*]" <temp1 >temp2
tr "[6*]" "[046+]" <temp2 >temp1
tr "[7+1" "[007+]" <temp1 >temp2
tr "[8*]" "[010*]" <temp2 >temp1
tr "[9*]" "[051*]" <temp1 >temp2
tr "[a*]" "[052*]" <temp2 >temp1
tr "[b*]" "[J13*]" <temp?
tr "[c*]" "[054*]" <temp2 >remp1
tr "[d*]" "[015+]" <temp1 >temp2
tr "[=+]" "[015+]" <temp2 >temp1
tr "[f*]" "[057*]" <temp1 > 42
rm temp1 temp2
```



APPENDIX F

ATAC PROGRAM

The following programs are listings of the Main System and Receiver Control programs for the ATAC. The assembly language is to the right of the absolute listing of the first three columns.



PAGE CARDNUM 22 33 44 10 112 112 113 114	1-048-1924-108 mmphphphphph	VM 4 W W W W W W W W W W W W W W W W W W	
03/21/77			
IMAGE IDT ATAC DS 0100 EQU 0500 EQU 0500 *********************************	ADDRESS OF INPUT BUFFER CONSTANT ZERO CONSTANT ONE LOWER BYTE OF REQUEST ADDRESS OF REQUESTED RPER BYTE OF REQUEST COUNT OF WOIDS IN BUFFER	GET TITLE ADDRESS OUTPUT TITLE GET PROGRAM REQUEST SAVE ALL REGISTERS	SET UP CONSTANT SET UP CONSTANT GET COUNT OF WORDS IN BUFFER INCREMENT BUFFER POINTER GET WORD FROM BUFFER DECREMENT WORD COUNT GET OUT IF NOT THERE COMPARE WITH SPACE IF SPACE KEEP LOOKING FOSTION UPPER BYTE POSITION LOWER BYTE
D IMAGE IDT ATAC DS 0100 ENTRY EXEC EQU 0500 ENTRY EX************************************	* 6000 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1	R D, EADD, ETITLE L I, RET, KEYNR RM D, 0, EXECS, 16 TWO LETTERS OF REQUE	LDR IS, EONE, 1 LDR IS, EZ, 0 LDR RX, EZ, EA, DD, EZ LDR RX, EU, EA, EX LDR RX, EU, EA, EX LDR RX, EU, EX LDR RX, EL, EA, EL, EA, EL, EX SHIS, LL, EL, EA, EX SHIS, LL, EX S
CARD II D9 D9 D8 ECC EXEC ** ** ** ** ** ** ** ** ** ** ** ** **	A D D O N E O O N E O O N E O O N E O O N E O O O N E O O O O	* * * C * * * C * * * C * * C * * C * C	×
CODE		140 230 151 136	0100
OBJECT		E201 ED000 ED000 9CF0	44 44 44 65 65 65 65 65 65 65 65 65 65 65 65 65
ATAC LOC 0000		0000 0100 0104 0106	00000000000000000000000000000000000000



PAGE	CARDNUM	55		00000	, CO	0000 0000 0000 0000	75.	76.	78	, \$\$\$\$\$\$\$\$\$ 1025	- @ & c)—(Vm:	960	0000 0000	0000 0000 0000	1005 106 107
03/21/77		4D														
TIME: 15:22:49		COMBINE FIRST TWO BYTES OF COMMAND	SEE IF REQUEST FOR WJ	PATCH AREA FOR ANOTHER REQUEST		RESTORE REGISTERS ECHO INPUT BUFFER GET ADDURESS OF CR/LF BUFFER GUTFUT CR/LF GO TRY AGAIN		GO TO WJ					SAVE AREA FOR REGISTERS	CR/LF	COUNT EX EX HULL	
	CARD IMAGE	IOR R, EU, EL	. CMP I BH 0776A BRCL EQ. BX2	MOP WOP WORLD	: ECHO EXIT - INVALID REQUEST	LDRH D, 0, EXECS, 16 EAL I, 0, OUTPUT BAL I, 0, OUTPUT BRC I, 7, EXEC	CALL RECEIVER CONTROL PROGRAM	Ex2 BAL I, RET WJ BRCL U, EXEC	: PATCH AREA FOR ANOTHER REQUEST	NOP		* * * * * * * * * * * * * * * * * * *	EXECS DS 20		ETITLE DC 3 04558 DC 04543 DC 0	
	OBJECT CODE	A446	B106 776A C102 012A	0000 0000 0000 0000		BCF0 0136 ED00 0230 E101 014A ED00 0230 C107 0100		ED 00 0500 C107 0100		00000 00000 00000 00000 00000 C107 0100				0001 000A	4559 4559 0000 0000 0000	
ATAC	TOC	0117	0118 0118	011C 011B 011E 011F		0120 0122 0124 0126 0128		012A 012C		012E 012F 0130 0131 0133 0133			0136	777	014D 014E 014F 0150	



PAGE	CAR DNUM 108 110 111 1112	1111 120 120 120	2002020 2002020 2005 2005 2005		20077 20077 20007	0.465 1.45 1.45 1.45 1.45 1.45 1.45 1.45 1.4	11114 1050 100 100 100	000 000 000 000	<u> </u>
03/21/77							R D	ENTRY	
TIME: 15:22:49	IMAGE ************* EQUATES ** ********* * * * * * * * * * * * *	RETU	A PROM THE KEYBOARD ** YMR ** **	ADDRESS OF BUFFER CONTAINING THE KEYBOARD * BUTRY (ONE CHARACTER PER WORD, RIGHT * JUSTIFIED, ASCII) THE FIRST WORD OF THE BUFFER CONTAINS THE * RUMBER OF CHARACTERS IN THE KEYBOARD *	•		RETURN REGISTER ADDRESS OF BUFFER HOLDING KEYBOAR ENTRY POSTITON COUNTER FOR NEXT INDUT	INPUT FROM KEYBOARD (CURSOR) MAX POSITION USED IN KEYBOARD EN'	OUTPUT REGISTER INPUT REGISTER OUTPUT REGISTER OUTPUT DEVICE ADDRESS VARIABLE 1
	**************************************	0 **	EDURE: L,O,KEYME	ADDRE CUSTI THE F NUMBE	E.	# * * * * * * * * * * * * * * * * * * *	0- 3	9	7 8 9 110
	A A MESH	*	INE TO READ ING PROCEDUI BAL I,	UTS:	OUTFUT PR	**************************************	EQU EQU	EQU	E E E E E E E E E E E E E E E E E E E
	CARD *** SYSTEM THESE PROGRA THE SY	RET **** ****	. ROUTIN . CALLIN	OUTPUTS	ROUTI	## ### ESTAB! ####################################	KRET KBUF	KPM	KOR KIR KOUT KIN KV1
	OBJECT CODE								
ATAC	207								



PAGE	CARDNUM	100 100 100 100 100 100 100 100 100 100	168 169 170	771 175 176 176	877 180 180 180	10000 10000 10000	1988 1988 1988 1988 1988	20000		203 203 203 203 203	2004 2004 2004 2004 2004	2222
щ	CAF											
03/21/77												
TIME: 15:22:49		VARIABLE 2 VARIABLE 3 INPUT DATA FROM KEYBOARD		SAVE RETURN ADDRESS GET ADDRESS OF RUFFER TO OUTPUT OUTPUT INITIAL BUFFER DEVICE ADDRESS FOR INPUT DEVICE ADDRESS FOR OUTPUT DOSITTON COMMTER = 1	MAX POSITION USED = 1 ADDRESS OF BUFFER TO REGISTER RESET CODE RESET KEYBOARD	LE SPACES *******	SET COUNTER TO BUFFER LENGTH GET BUFFER ADDRESS CODE FOR SPACE STORE BLANK CODE DECREBENT COUNTER DO AGAIN IF COUNTER		RESET CODE RESET KEYBOARD	GET DATA DATA PRESENT ? NO DATA, WAIT	RESET CODE RESET KEYBOARU GET STATUL DATA STIUL PRESENT? KEBP TRYING TO CLEAR	
		14 14	****************	D, KRET, RETURN I, KBUF, KBSTRT I, KRET OUTPUT I, KIN, OPFBR I, KOL, OBFFR	ISKBUFKBUFFER IKOR 68000 KOR, KOUT	**************************************	15 KV1 60 R KV2 KBUF IS, KV3, 020 IS, KV1 - 1 GT, KM R2	**************************************	I KOR 08000 KOR, KOUT	KDATA, KIN I, KDATA, 04000 NE, KMR4	I KOR 08000 KOR KUUT KIRKIN I KR 02000 EQ.KMR5	
	D IMAGE	000 000 000 000 000 000 000 000 000 00	ALIZE A	STR LOR BAL LOR LOR	LDR LDR LDR ROUT	****** EYBOARD *****	LDR LDR LDR STR ADD BRCL	******* ATA FRO ******	LDR	RIN CMPL BRCL	LDR ROUT RIN CMPL BRCL	****** OBTAINE ******
	CARE	KW2 KW3 KDATA	* L + * * * * * * * * * * * * * * * * *	KEYHR Kmr1		SET KE	KMR2	GET DI	K MR3	K MR4	řmr5	. DATA
	r CODE			0 106 0228 0230 PFBF BFFF	0107 8000		0165		0008	4000 016C	8000 2000 0171	
	OBJECT			9C00 E1010 E100A E100A	016 101 997		450B E01C 420D 1BCD 6FFB		E107 8	9E0E 0	E107 D997 8CA8 9E08	
AT AC	TOC			000000 100000 100000000000000000000000	10000		0162 0163 0164 0165 0166		0169 016B	016C 016D 016F	0171 0173 0174 0175	



PAGE	CARDNUM	214	222222 2223 223 223 223	222	00000000000000000000000000000000000000	777 733 733 733 733 733 733 733 733 733	777 779 779 779 779 779 779 779 779 779	233 238 238 238	2543 2443 2443	25 to	22470	2227 225 2104 2104	2222 2253 2553 2553 2553 2553 2553 2553	7520 7520 1520 1520 1520 1520 1520 1520 1520 1	7 7 7 7 7 7 7 7 7 7 7 7 7 7 7 7 7 7 7	265 265 265 265 265 265
03/21/77																
TIME: 15:22:49		SAVE DATA ONLY	OMPARE WITH OT BACKSPAC ECREMENT PO OOK FOR DAT	GET MORE DATA	COMPARE WITH FORWARD SPACE NOT FORMARD SPACE INCREMENT POSITION COUNTER COMPARE WITH MAX VALUE LESS OR EQUAL MAX GET MORE DATA SET POSITION COUNTER TO 80 GET OUT OF ROUTINE	COMPARE WITH CARRIAGE RETURN CR, GET OUT	COMPARE WITH DECIMAL POINT BECIMAL POINT, FUT IN BUPFER	COMPARE WITH SPACE SPACE, PUT IN BUFFER	COMPARE WITH O ILLEGAL CHARACTER	COMPARE WITH 9 NUMERIC, PUT IN BUFFER	COMPARE WITH UPPER CASE A ILLEGAL CHARACTER	COMPARE WITH UPPER CASE Z UPPER CASE ALPHA, PUT IN BUFFER	COMPARE WITH LOWER CASE A ILLEGAL CHARACTER	COMPARE WITH LOWER CASE Z LOWER CASE ALPHA, PUT IN BUFFER		GET ADDRESS OF ILLEGAL BUFFER OUTPUT BUFFER START OVER
		I.KDATA.0007F	S KDATA S KREG S KREG S KREG S KREG	KHR	IS, KDATA, 01C NE, KMR8 IS, KPC, 1 IS, KPC, 80 LE, KMR, 8 I, KPC, 80 U, KMR, 1	IS, KDATA, 00D EQ, KMR11	IS, KDATA, 02E EQ, KMR10	IS, KDATA, 020 EQ, KHR10	IS, KDATA, 030 LT, KMR9	IS, KDATA, 039 LE, KMR10	IS, KDATA, 041 LT, KMR9	IS, KDATA, 05A LE, KMR10	IS, KDATA, 061 LT, KMR9	IS, KDATA, 07A LE, KMR10	* > *	I, KBUF, KBILL I, KRET, OUTPUT U, KMR1
	RD IMAGE	QN A	CMP BRCL ADD BRCL	BRCL	CMP BRCL ADD CMP BRCL LDR BRCL	CMP BRCL	CMP BRCL	CMP BRC L	CMP BRCL	CMP BRCL	CMP	CMP BRCL	CMP BRCL	CMP BRCL	******* GAL ENTR *****	LDR BAL BRC L
	CAI	•	•	,	KMR6 KMR7	KMR 8	•	•	•	•	•	•	•	•	***** . ILLEC	KMR9
	ECT CODE	007F	8 9	0169	0190 0050 0169 0050 0189	01189	0181	0181	OIAB	0181	OIAB	0181	OIAB	0181		022C 0230 0153
	OBJEC	A10E	108 108	10	21CE 60105 60105 C1005 C1005 C1005	20 DE C 1 02	22EE C102	220E C102	230E C104	239E C106	241E C104	25AE C106	261E C104	27 AE C106		E101 ED00 C107
ATAC	TOC	0.179	7177	100	0184 0185 0187 0188 0188 018E	0190	0193 0194	0 196 0 197	0199 019A	019C 019D	019F 01A0	01A2 01A3	0185	01A8 01A9		01AB 01AD 01AF



ATAC	OBJECT	T CODE	Š	RD TMAGE		TIME: 15:22:49 03/21/77	PAGE
2		3	* * *	* * * * * * * * * * * * * * * * * * *	**************************************		267 268 268 269 269
0181 0183 0184 0186 0186	985E 8056 C103 E056 C107	01D7 0187 0187	KMR10	STR CMP BRCL LDR BRCL	DX,KDATA,KBUFFER,KPC RKPM,KPC GE,KMR7 RKPM,KPC U,KMR7	COMPARE MAX USED WITH LAST POSITIO GO INCHEMENT POSITION COUNTER PC FC	222222 222222 242222 2432
			**** EXIT ****				272 273 278
0189	9006	01107	MR 1 1	STR		PUT COUNT IN BUFFER	281 281
001009 001009 001009 001009 001009 001009	E018 4005 6018 6018 6018 6018 6018 6018 6018 6018	0103 018D 018D 010B 02F8	REMO REMO R30	IS THE CONTROL OF THE PROPERTY	UENCE FOR ERACTE FOR EVALL EVALL EVEL EVAL	BETWEEN DOTTED LINES MAY BE HO LONGER DESTRED. DDRESS OF CALLING ROUTINE OCESS CORE REQUEST	
0103	E200 BF07	0106	KMR 12	LDR	D, KRET RETURN R,7, KRET	N N	100000 1000000 10000000000000000000000
			DATA				16000000 16000000 16000000
0106			ETURN ***	DS	DS 4********	RETURN ADDRESS STORAGE	316 3117 319



PAGE	CARDNUM	320	3237 3237 3333 3333 3337	327 327 337 337 337 337 337 337 337 337	nadadu Nationa Nationa DO + Nati	nemen nem nem	10000000000000000000000000000000000000	12 CO	0000 0000 0000	350 100 100 100 100	-200 -200 -200 -200 -200 -200 -200 -200	1001 1001 1001	JEIMEINE 1000000 10000000000000000000000000000	1000 1000 1000 1000	0900 3000 3000 3000 3000 3000 3000 3000	360 370 371
03/21/77																
TIME: 15:22:49			COUNT		COUNT CR/LF + NULL		COUNT CR BELL BELL, BELL NULL,		****		****	TO BE OUTPUT	* IN THE FOLLOWING MANNER: * OF WORDS IN BUFFER TO BE OUTPUT * TO BE OUTPUT, TWO ASCII *	* * * *	***	**************************************
	CARD IMAGE	KEYBOARD ENTRY BUFFER	KBUFFER DC 80 DS 80	**************************************	KBSTRT DC 3 0000A DC 002B DC 00000	. ILLEGAL CHARACTER BUFFER ***********************************	ŘВІL I DC 3 00 A07 DC 00707 DC 00000		*****************************	ROUTINE TO OUTPUT TO THE TTY/CRT	. CALLING PROCEDURE: BAL I,0,0UTPUT	INPUTS: ADDRESS OF BUFFER	THE BUFFER MUST BE SET UP IN T MORD 1 N = NUMBER OF WO HORDS 2-N ASCII DATA TO BE CHARACTERS PER W	OUTPUTS:	ROUTINES CALLED:	. THIS ROUTINE PRESERVES NO REGI:
	OBJECT CODE		0020		00003 00008 0002B		00 03 00 07 07 07 00 00									
ATAC	TOC		01D7 01D8		0228 0229 0224 0228		022C 022D 022D 022E 022E									





PAGE	CARDNUM	22222	າຕາຕາເ	10000000000000000000000000000000000000	***	ֈՠ֍ՠ֍ՠ	വസവാവ	9	9999	9999	200	ーレーレ	ーーーに	-
11/12/60														
TIME: 15:22:49		IN THE OUTPUT BUPFER INCREMENT OUTPUT BUPPER POINTER DECKEMENT NUMBER OF WORDS TO INPUT DO AGAIN IP NOT FINISHED		GET ADDRESS OF OUTPUT BUFFER GET STATUS COMPARE STATUS COMPARE STATUS COMPARE STATUS GET CHARACTER TO OUTPUT CLEAR ALL BUT OUTPUT DATA OUTPUT A CHARACTER DECREMENT BUFFER POINTER GO OUTPUT ANOTHER CHARACTER		GET EXCESS COUNT GET OUT IF ZERO DECREMENT BY 40 DO AGAIN		SAVE LOCATION POR EXCESS COUNT	OUTPUT BUFFER	****	***	***	CONVERTED (INTEGER)	***
	62	IS, BO, 2 IS, WI - 1 GT, OUF 1	****** BUPFER ******	STAT VIN STAT VIN STAT VIN NE WOUT O BO I GOUT OO FF IS BO 1 IS BO 1 IS BO 1		D, WI, COUNT Z, OUT4 U, OUT5 R, 7, RET		_	80	语名 安安安安 安安	CONVERT HEX TO ASCIT	EDURE: I,0,HEXA	HEX VALUE TO BE CO	
	RD IMAGE	ADD ADD BRCL	********	LDDR CMPL BRCL ILC ILC ADD ADD BRCL		LDR BRCL ADD BRCL BRCL		DS	DS	* * *	NE TO	ING PROCE	UTS:	PUTS:
	CA		**** OUTP	0 UT 2	**** EXIT ****	• 0 UT4	**** DATA ****	COUNT	BUFOUT	**** HEXA	. ROUTI	CALL	INP	: ourp
	OBJECT CODE	25 FB 01 0246		05 026 B 026 B 05 026 B 05 025 U 00 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0		0B 026A 02 0269 8B 07 0237								
AT AC	LOC OB	024E 602 024F 6F1 0250 C10		00255 0025 00		0262 E20 0264 C10 0266 600 0267 C10 0267 C10		026A	0268					



PAGE	CAR D V U M D V U U M D	1244444 00000000000000000000000000000000	Դ Դ Դ Դ Դ Դ Դ Դ Դ Դ Դ Դ Դ Դ Դ Դ Դ Դ Դ	9008 9008 1008 1008
TT/177		OUTPUT OUTPUT		
TIME: 15:22:4	TWO DIGITS IN ASCII ** R CASE ************************************	HEX VALUE INPUT MOST SIGNIFICANT DIGITS TO C LEAST SIGNIFICANT DIGITS TO VARIABLE	SAVE RETURN REGISTER GET HEX INPUT VALUE RIGHT JUSTIFY FIRST CONVERT FIRST DIGIT POSITION DIGIT POSITION DIGIT ROST HEX INPUT REGISTER GET HEX INPUT VALUE RIGHT JUSTIFY SECOND DIGIT CLEAR ALL BUT SECOND DIGIT RUT IN OUTPUT REGISTER GET HEX INPUT VALUE CLEAR ALL BUT THIRD DIGIT RIGHT JUSTIFY THIRD DIGIT RIGHT JUSTIFY THIRD DIGIT RIGHT JUSTIFY THIRD DIGIT RIGHT JUSTIFY THIRD DIGIT ROST HEX INPUT VALUE CLEAR ALL BUT THIRD DIGIT RUT IN OUTPUT REGISTER GET HEX INPUT VALUE CLEAR ALL BUT FOURTH DIGIT CONVERT FOURTH DIGIT RUTH DIGIT RUTH REGISTER	
	GE MOST SIGNIFICANT LEAST SIGNIFICANT LEAST SIGNIFICANT LEAST SIGNIFICANT LED: ALLED: B DOES NOT DISTURB ***********************************	2233334 tq. 4************************************	D, RET HEXRIN RET, HEXRI LL VI HEXAL R. NSD VI R. VI GOOUF I VI GOOUF I VI GOOUF I RET, HEXAL I RET, HEXAL	
	CARD IMA REG 3 REG 3 LETTER ROUTINES C NONE THIS ROUTI ************************************	IN EQU	EXA LOTAL BANDALS ANDALS A	*** **** ****
	CODE	·EEJ> · · · · · ·	181 H	
	OBJECT		9C0000200000000000000000000000000000000	
£)	Гос		00000000000000000000000000000000000000	



PAGE	CARDNUM	532 532 533	ນ ການ ການ ການ ການ ການ ການ ການ ການ ການ ກາ	0.00 Emar 10.00	- 2000 -	1000t	ეტი 12 12 12 12 12 12 12 12 12 12 12 12 12 12 12 12 1	արասան Մարսան Մարսան Մարսա	i Nana Inanana Inananana Inanananananananan	200 200 200 200 200 200	いいいちらい 600001 240000	569 570	572 573 573	572 576 576 576	727 728 728 728 728 728 728 728 728 728	2000 2000 2000 2000 2000 2000 2000 200
03/21/77																
ME: 15:22:49				Α.	CALLED FROM		RETURN ADDRESS	* * * * * * * * * * * * * * * * * * *	I THE **	* * * 1	IN	6 38 35 4	* * * *	* * * * * * * * * * * * * * * * * * * *		CHARACTERS
TIL		GET RETURN ADDRESS RETURN		CI	LUE		SAVE LOCATION FOR	****	LESS DIGITS IN ASCI E MACHINE, SIGN OF LLING ROUTINE.		CONSECUTIVE LOCATIO CII CHARACTERS ARE R CORE LOCATION)			ERVED		ADDRESS OF ASCII COUTPUT HEX VALUE VARIABLE 1
	EL)	D, RET, HEXRTN R, 7, RET	****** DIGIL 10 GIL	IS,V	IS,V1,7 IS,V1,0 R,,RET		-	**************	CONVERT FOUR (4) OR RUE HEX VALUE FOR TH BE HANDLED BY THE CA	CEDURE: I, 0, AHEX	ADDRESS OF FIRST CORE WHERE THE AS (ONE CHARACTER PE	HEX VALUE	LLED:	8 THROUGH 16 ARE PRES	***** EQ U A T ES ******	5
	CARD IMAGE	LDR	**************************************	_	2 ADD BRC	* « *	rn DS	* * * * * * * * * * * * * * * * * * *	JTINE TO CO JE TO A TRU SUE MUST BI	ž	INPUTS: REG 1	OUTPUT: REG 2	ROUTINES CA	STERS	*************************************	E E E E E E E E E E E E E E E E E E E
			00	HEXA	HEXA	****	HEXRTN	.**** . AHEX	ROUTIL CODE	: CALLI	IN I	. 001	ROI	. REGI	* 50 *	AHADE AHOUT AHV1
	OBJECT CODE	E200 02E1 BF07		20 A4 C104 02DF	60 74 6304 BF 07											
AT AC	201	02DB 02DA		020B 020C	02DE 02DF 02E0		02E1									

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PAGE	CARDNUE	17772 17772	7007 7005 7005 7007 7008	77777777 2777777777 2017777777 20178	1758 1758 1758	//////////////////////////////////////	739	742
TIME: 15:22:49 03/21/77		ERS INPUT BY KFYMR SPACE		ESS FOR TITLE FLAG MMAND STANT GISTER		TES IN BUFFER RADDRESS CTER COUNTER ACE PACE E OF ENTRY	ADDRESS NG TO FIELD FOUND	
		VARIABLE 3 MAX NO. CHARACTER PATH FLAG BLANK FLAG FIELD2 CONTAINT O ASCNIT CODE FOR SP VARIABLE 1 COMMAND FIELD 1		SAVE REGISTER 2 GET A ZERO INTIALIZE SEQUI GUTPUT TITLE GET REYBOARD COL SET UP ZERO CON SET UP ZERO CON ZERO FIELD 1 ZERO FIELD 2 ZERO FIELD 2 ZERO FLAG ZERO PLAG		GET NO, OF BNIR SET FLAG FOR RE, INCREMENT BUFFED DONE GET A CHARACTER COMPARE WITH SP KEEP GOING IF S SEE IF IN MIDDL IN ENTRY, KEEP	GET PROCESSING PROCESS ACCORDI	
		55 50 110 112 15 15 15		D 2 CSAVE I 5 CV 1 0 D CV 1 CSFLG I CAD CSFLG I RET OUTILE I RET KEYNR I S CSERCE 0 2020 I S CMD 0 I S CFL 0	***** MMAND *****	RX, CHAX, CZERO, CADD IS, CFLG, 0 IS, CAAX, -1 IS, CCAAX, -1 NP, CV1, CZERO, CADD IS, CV1, 020 ES, CFLG, 0 NB, C3	DX, RET, CFLD, CINDX R, 7, RET	
	RD IMAGE	# DD	* & * * = *	S T T T T T T T T T T T T T T T T T T T	****** \$LATE CO	LDR LDR ADD ADD BRCL LDR CMP CMP CMP BRCL	LDR BRC	CH TABLE
	CA	CV3 CCHAX CINDX CFLG CFLG CFLG CZERO CSPACE CV1	* * * * * * * * * * * * * * * * * * *	CORE C1	 TRA.* ***	. CC2		. BRAN
	T CODE			0303 0405 02405 00151 20151		0327 030C 030D	031B	
	OBJECT			44000F 4000B 4000B 4000B 4000B 4000B		51A6 64018 64018 64018 671AC 72002 72002 72003 72003	E370 BF07	
AT AC	LOC			0021FB 0027FB 003001 003003 003003 003009 003009		0300 0300 0300 0310 0311 0311 0311 0311	0318 031A	



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03/21/77									۵				
TIME: 15:22:49		C4 COMMAND FIELD FIELD C6 FIELD 7	ADDRESS OF COMMAND INCREHENT PATH INDEX SET FLAG FOR IN ENTRY KEEP GOING ADDRESS OF FIELD 1 KEEP GOING ADDRESS OF FIELD 2	SEE IF FIELD 1 IS PRESENT GO PROCESS COMMAND ONLY	PHT ADDRESS IN REGISTER CONVERT VALUE PUT HEX VALUE IN FIELD	SEE IF FIELD 2 IS PRESENT GO PROCESS COMMAND	PUT ADDRESS IN REGISTER CONVERT VALUE PUT HEX VALUE IN FIELD		GET FIRST CHARACTER OF COMMAND INCREMENT ADDRESS GET SECOND CHARACTER OF COMMAND CLEAR UPPER BITS LEFT 15T CHARACTER IN ONE WORD PUT IST 2 CHARACTERS IN ONE WORD	COMPARE WITH "DO" GO PROCESS DOWE	COMPARE WITH "DU" GO PROCESS DUMP	COMPARE WITH 'DI' GO PROCESS DISPIAY	COMPARE WITH "CH"
			R CMD CADD IS CINDX I IS CFI.G 1 IS CFI.CADD U.C7 R,CF2,CADD	IS,CF1,0 EQ,C8 D 1 TO HEX	R, CADD CF1 I, RET, AHEX R, CF1, CA1	IS,CF2,0 EQ,C8	R, CADD C I, RET, AH	OCESS ON COMMAND	RX,CV1,CZERO,CMD IS,CMD,1 RX,CV2,CZERO,CMD LI,CV2,600FF LI,CV4,68 R,CV1,CV2	I CV1,0646F	I CV1 06475	I, CV1 06469	I,CV1,06368
	E CARD IMAGE	CFLD DC DC DC	C4 LDR DD ADD LDR C5 LDR C6 LDR	C6A CMP BRCL : CONVERT FIELD	LDR BAL LDR	CMP BRCL BRCL	NVENT FIEL LOR EAL LOR LOR	. BRANCH TO PRO	Č8 LDR ADD LDR AND SHS ADD	CAPBRCL	. CAP. BRCL	CMP BRCL	CMP
	COD		03 0D 03 1 F	0335	02E2	0335	02E2		0 OF F	646F 0352	6475	6469	8368
	OBJECT	031E 0323 0326	E01E 6017 4PF8 C107 E01F E019	200F C102	E0F1 ED00 E02F	2009 C102	E091 ED00 E029		5EAC 601E 5EAD A10D AE7C 80DC	B10C C102	B10C C102	B10C C102	B10C
ATAC	TOC	03 18 03 1C 03 1D	0311 0321 0321 0321 0323 0324	0327 0328	032A 032B 032D	032E 032F	0331 0331 0334		0335 0334 0334 0338 0338 0338	033C 033E	0340	0346	0348



PAGE	CARDNUM	197	7 9 9 9 9 9 9 9 9	805 803	2000 2000 2004 2004 2004 2004 2004 2004	8888 8812 01218	######################################	0F25 8825 8825	825 825	827 827 828	823 830 830 830 830	a Segan Segan Segan	8837 837 838 838 838	00000000000000000000000000000000000000	80 80 80 80 80 80 80 80 80 80 80 80 80 8	848
03/21/77																
TIME: 15:22:49		GO PROCESS "CHANGE"	COMPARE WITH "CS" GO PROCESS CHANGE SEQUENTIAL	INVALID COMMAND, GO TRY AGAIN		GET ADDRESS OF CALLING ROUTINE EXIT THROUGH KEYMR		CLEAR LAST THRRE BITS SET UP ADDRESS TO DUMP SET UP LINE COUNTER	OF FIRST VALUE	SET UP OUTPUT BUFFER ADDRESS SET UP ROW COUNTER	SET UP INPUT FOR HEXA CONVERT ADDRESS TO ASCII FUT MSD OF ADD IN OUTPUT BUFFER	PUT LED OF AND IN COUNCES INCREMENT BUFFER ADDRESS FUT IN SPACES	INCREMENT BUFFER ADDRESS PUT IN SPACES INCREMENT BUFFER ADDRESS	THE WALLE TO CONTROL TO CONTROL TO CONTROL VALUE FOR MSD OF VALUE INCREMENT BURFER	PUT LSD OF VALUE IN CUTPUT BUFFER INCREMENT ROW COUNTER COMPARE SITH LAST VALUE	GO DO ANOTHER VALUE GET DUFFER POINTER
		EQ,C12	I,CV1,06373 EQ,C26	U,C1		D, O, CSAVE I, 7, KEYMR		I,CF1,OFFP8 R,CV3,CF1 IS,CIMDX,10	OF CORE WITH ADDRESS	I, CV1, CBUFF R, CV2, CZERO	R, CADD, CV3 I, RET, HEXA RX, CA1, CV1, CZ ERO	RX,CA2,CV1,CZERO IS,CV1,1 RX,CSPACE,CV1,CZERO	IS,CV1,1 RX,CSPACE,CV1,CZERU IS,CV11, CV3, CYFFRO	IX CAP 1 CAP	RX CA2 CV1,CZERO IS CV2,1 IS CV2,8	U, CAUD, CBUFF
	IMAGE	BRCL	CMP BRCL	BRCL		LDR BRC		AND LDR LDR	LINE					ADD BAL STR		
	CARD		•	•	* 2 * * * * * * * * * * * * * * * * * *	6.2	*** *** ***	ċ10	. ourpur	¢13			C 1 4			C15
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03/21/77		ET		
DECREMENT BY ONE TO GET COUNT	RESTORE REGISTERS DECREMENT LINE COUNTER DO ANOTHER LINE WAIT FOR ANOTHER COMMAND	GET ADD OF LOCATION TO DISPLAY CONVERT CORE CONTENES TO ASCII PUT HSD IN OUTPUT BUFFER PUT CORE VALUE IN REGISTER CONVERT ADDRESS TO ASCII PUT ASD IN OUTPUT BUFFER PUT ADDRESS IN REGISTER OUTPUT BUFFER COUTPUT BUFFER		CHANGE CORE CONTENTS GO DISPLAY CORE CHANGE
IS CADD, -1	Drocking of the control of the contr	R.CADD CF1 I.RET.HEXA D.CALCBUD11 D.CAZCBDD141 D.CAZCBDD O.CF1 I.RET.HEXA D.CALCBUD241 I.CADD CBUD241 I.RET.CADD I.RET.CADD I.CADD I.RET.CASFLG I.CADD I.RET.CSFLG I.7.C1		DX, CF2, 0, CP1
CARD IMAGE	LDRD LDRD ADD BRCL BRCL BRCL BRCL BRCL BRCL BRCL BRCL	C.11 LDR BALL STR STR LDR LDR LDR LDR LDR LDR LDR BRCL BRCL	CH ***	C12 STR BRC
BJECT C	ELFO 03F3 6FF7 C105 03FA C107 02FD	E0F1 E0F1 ED00 02B 9C03 0408 E3F1 0000 E000 E000 E000 E000 E100 E		9BF9 0000 C107 0383

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03/21/77			ੇ ਤ
TIME: 15:22:49	COUNT CRAFF ON INTERNAL USE CRAFF CO	COUNT 2 LOCATIONS FOR ADDRESS BLANKS 2 LOCATIONS FOR CONTENTS CR/LF	START ADDRESS FOR SEQUENTIAL CORE CURRENT ADDRESS FOR STORING IN SEQ FLAG FOR SEQUENTIAL CHANGE
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IMAGE		95 95 95 95 95	DC DC DC
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03/18/77								V R
16:43:42								WORDS FOR RC NTO CONTROL WORD DISPLAY
TIME:					¥ 2~ 0~≈		N ADDRESS	CONTROL VALUES I CONTROL L CONTROL
					XARR END XARR END XARR 2 XARR 3 XARR 4 DATA 1 DATA 2 DATA 3 DATA 3 DATA 3 VARIABLE 3 VARIABLE 3 VARIABLE 9 VARIABLE 6 VARIABLE 6 VARIABLE 6 VARIABLE 6 VARIABLE 6 VARIABLE 9 VARIABLE 9 VAR		SAVE RETUR	GET INITIAL PUT INITIAL GET INITIAL SAVE INITIAL
		AFAC 0500 WJ	0 00230 00151	* * * * * * * * * * * * * * * * * * *	2100 0110 0110 0110		D, RET, WJRET ****** ECELVER ******	D, HJV1, HJI1, 4 D, HJV1, HJCCD, 8 D, HJV1, HJCCD, 8 D, HJV1, WJCFL, 8
	IMAGE	IDT DS ENTRY	EQU EQU EQU	****** ISH EQU			STR ***** LIZE R ****	LDRM STRM LDRM STRM
	CARD		RET OUTPUT KEYMR	ESTAB*	O-O FILLO FOR TO CONTROL TENDERS FOR TO CONTROL TO CONTROL TO CONTROL TO CONTROL TO CONTROL TO CONTROL TO CONT	**************************************	******* ******	4 J01
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03/18/77		್ನೂ ಆಗ್				EL		DRD CONTRO			
TIME: 16:43:42		LOAD "ADDRESS ON" ENABLE RECEIVER/TURN ON INTERFAC. CLEAR REGISTER CLEAR FLAG ZERO WJS COUNTER ZEND INITIAL CONTROL WORD TO RCVI GET ADDRESS OF INSTRUCTION BUFFER OUTPUT INSTRUCTION BUFFER OUTPUT TITLE AND GET ENTRY		COMPARE WITH ONE WILL ONLY ACCEPT ONE CHAR COMPARE WITH MAX VALUE ENTRY OUT OF RANGE		GET ADDRESS FOR BRANCH FROM TABL GO PROCESS ACCORDING TO COMMAND	OPERATOR	0=SET UP TENTATIVE WORD 1=DISPLAY TENTATIVE CONTROL WORD 2=DISPLAY CANTROL WORD 4=ENTER TENTATIVE WORD AS NEW CO 5=SCAN 6=RECEIVE CONTROL WORD FROM RCVE 7=DONE 8=REINITIALIZE		NTRY FOR FREQUENCY	GET ADDRESS OF FREQUENCY TITLE OUTPUT TITLE AND GET ENTRY ILLEGAL ENTRY MAKE SURE FREQUENCY IS LEGAL
	Ω1.	D WJX1 WJCRO I WJXS CH KPLG I D WJXS CH KPLG I I KBT WJ I WJ I I KBT CU IPUT I KBT CU IPUT I KBT CU IPUT	***** OMM & ND *****	IS, MJV2, 1 NE, WJ02 IS, WJV3, 8 GT, WJ02	**************************************	DX, RET, WJBRC, HJV3	E FOR COMMANDS FROM	XEXESO 1070 1070 1070 1080 1080	7 ************************************	E AND GET KEYBOARD E	I , WJV1 HJFB I, RET 6190 U, HJ10 I, RET, HJ91
	IMAGE	LLC ROUT LDR STR STR BAL LDR BAL BAL	****** ******	CMP BRCL CMP BRCL	***** ******	LUB BRC	TABLE		***** ***** ****	TITLE	LDB BAL BRCL BAL
	CARD		# * * * * * * * * * * * * * * * * * * *		****** BRANCH ******	•	BRANCH	#JBRC	***** SET UP	: OUTPUT	¥J10
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TIME: 16:43:42 03/18/77	N 20 20 20 20 20 20 20 20 20 20 20 20 20	STORE TEN STORE TEN STORE TEN	GET ADDRESS OF DEFECT HODE TITLE OUTPUT TITLE AND GET ENTRY LILEGALE ENIRY COMPARE HITH MAX VALUE TOO LARGE SAVE TENTATIVE DEFECT HODE GET UPPER OF DEFAULT BFO FREQUENCY SAVE TENTATIVE BFO FREQUENCY GET LOWER OF DEFAULT BFO FREQUENCY COMPARE DEFECT HODE WITH BFO HOT VARIABLE BFO, USE DEFAULT FREQUE	BUTRY FOR BFU FREQUENCY	GET ADDRESS OF BPO FREQUENCY TITLE ILLEGAL ENTRY COMPARE WITH EXACT COUNT WRONG COUNT FOSITION FREQUENCY (10 HZ RES) COMPARE UNTRY COMPARE LOWER WITH MIN VALUE ILLEGAL ENTRY COMPARE LOWER WITH MIN VALUE ILLEGAL ENTRY COMPARE LOWER WITH MAX VALUE ILLEGAL ENTRY SAVE TENTATIVE BPO FREQUENCY (UPPER) SAVE TENTATIVE BPO FREQUENCY	ENTRY FOR GAIN MODE	GAIN HO GEL AX VALU NTRY FO DEFECT SE ISB	SAVE TENTATI ENTRY FOR IF BA
	1 2	D, MJV3, MJTEL D, MJV4, MJTFU AND GET KEYBOARD	1, RET 1, 19 0 15, RET 1, 19 0 15, HJV3, 7 67, HJV3, 7 67, HJV3, 7 10, HJV3, 19 0 10, HJV3, 19 10 10, HJV1, HJTBL 10, HJV1, HJTBL 10, HJV3, 3, 3 18 18 18 18 18 18 18 18 18 18 18 18 18	AND GET KEYBOARD	I MET 430 I MET 430 IS WAY 6 IS WAY 2,6 NE WAY 3,4 RE WAY 3,4 NE WAY 3,4 NE WAY 3,04 I MAY 3,04 I MAY 3,05 I MAY 3,0	AND GET KEYBOARD		D, 43V3, 4JTGM AND GET KEYBOARD
	MA	STR STR TITLE	LDR BAL BAC BBRCL STR LDR STR CAT BRCL	TITLE	EDR BAL BRAL BRRCL BRRCL SHD CRNP CRNP BRCL STR STR	TITLE	LDR BAL CCMP CCMP CCMP CCMP CCMP CCMP BRCL CCMP CCMP BRCL	TR
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TIME: 16:43:42		GET TENTATICOMPARE WITH NOT SIDEBAND COMPARE WITH NOT SIDEBAND SIDEBAND SIDEBAND SET POT SET SAW SET ENTERNAME WITH SAW SET ENTERNAME WITH SAW SET SAW	GET ADDRESS OF COMPARE MITH COMPARE HITH COMPARE HITH COMPARE ENTRY SAVE TENTRY SAVE TENTRY GO GET ANOTHE	GET UPPER OF TENTATIVE FREQUENCY GET LOWER OF TENTATIVE FREQUENCY BUT FREQUENCY IN BUFFER AND DISPL, GET TENTATIVE GAIN MODE GET TENTATIVE IP BANDWIDTH OUTPUT GAIN MODE AND IF BANDWIDTH GET TENTATIVE BFO BEFECT MODE GET TENTATIVE BFO FREQUENCY OUTPUT DETECT MODE AND BFO FREQUENCY OUTPUT RF GAIN DONE
			### ### ##############################	D. HJV2, HJTFU D. HJV1, HJTFU I HJV1, HJTGH D. HJV2, HJTJE I RET (J93 I HJV2, HJTDH D. HJV2, HJTBL I RET (J94 U. HJO2, HJRFG
	IMAGE	COMPRESS OF THE PROPERTY OF TH	*** C L P P P P P P P P P P P P P P P P P P	LUR LUBAL LUBAL LUBAL LUBAL BADL BADL BADL BADL
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* ~	GET UPPER OF CONTROL PREQUENCY GET LOWER OF CONTROL FREQUENCY OUTPUT PREQUENCY GET CONTROL GAIN HODE GET CONTROL IF BANDWIDTH OUTPUT GAIN HODE GET CONTROL DETECT HODE GET CONTROL BFO PREQUENCY GET CONTROL BFO PREQUENCY GET CONTROL BFO FREQUENCY GET CONTROL BFO AIN OUTPUT RF GAIN	***	GET UPPER OF RECEIVED FREQUENCY GUTPUT FREQUENCY GUTPUT FREQUENCY GUTPUT GAIN MODE GET RECEIVED IF BANDHIDTH GUTPUT GAIN MODE AND IF BANDHIDTH GUTPUT GAIN MODE AND IF BANDHIDTH GUTPUT BECEIVED BFO PREQUENCY GUTPUT BECEIVED BFO PREQUENCY GUTPUT BF GAIN GUTPUT BETECT MODE AND BFO PREQUENCY GET RECEIVED RF GAIN GUTPUT BF GAIN CLEAR REGISTER POSITION 15T DIGIT STORE IN OUTPUT BUFFER CONVERT TO ASCII STORE IN OUTPUT BUFFER GET ADDRESS OF BUFFER TO OUTPUT STORE IN OUTPUT BUFFER GET ADDRESS OF BUFFER DONE SPACE FOR PATCHES
CARD IMAGE ************************************	O LDR D NJV2, NJCFU LDR D NJV2, NJCFU LDR D NJV1, NJCFU LDR D NJV1, NJCGN LDR D NJV1, NJCIR LDR D NJV2, NJCIR LDR D NJV2, NJCIR LDR D NJV2, NJCBL LDR D NJV2, NJCBL LDR D NJV2, NJCBL LDR D NJV2, NJCBL LDR D NJV2, NJCFG LDR D NJV2, NJCFG LDR D NJV2, NJCRFG LDR D NJV2, NJCRFG LDR D NJV2, NJCRFG LDR D NJV2, NJCRFG	**************************************	HJ40 LDR D HJV2, HJRFU LDR
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TIME: 16:43:42 03/18/77		INITIALIZE PASS COUNT GET ADDRESS OF SCAN TIFLE OUTPUT SCAN TITLE SPACE FOR PATCHES	ENCY LIMIT	GET ADDRESS OF START FREQUENCY TITLE OUTPUT TITLE AND GET ENTRY HAKE SORE PREQ IS IN LEGAL BOUNDS ILLEGAL ENTRY SAVE LOWER LIMIT (LOWER) SAVE LOWER LIMIT (UPPER) SPACE FOR PATCHES	SNCY LIMIT	GET ADDRESS OF END FREQ TITLE OUTDUT TITLE AND GET ENTRY ILLEGAL ENTRY MAKE SURE FREQ IS IN LEGAL BOUNDS ILLEGAL ENTRY SAVE UPPER LIMIT (LOWER) SPACE FOR PATCHES	AN LOWER LIMIT	GET LOWER LIMIT (UPPER) COMPARE UPPER AND LOWER NO NEED TO CHECK FURTHER GET LOWER LIMIT (LOWER) GET LOWER LIMIT (LOWER) COMPARE UPPER AND LOWER LESS ON EQUAL, TRY AGAIN	NCREMENT (8000HZ MAX)	GET ADDRESS OF FREQ INC TITLE OUTPUT TITLE AND GET ENTRY ILLEGAL ENTRY POSITION LINCREMENT COMPARE COUNT WITH MAX ILLEGAL - TOO LANGE COMPARE HITH MAX ILLEGAL - TOO LANGE COMPARE WITH MAX INCREMENT ILLEGAL - TOO SAAL ILLEGAL - TOO SAAL SAVE INCREMENT SAVE INCREMENT SPACE FOR PATCHES
		D, WJV1, WJSCNT I, WJV1 WJSCAN I, RET, OUTPUT	AND GET LOWER FREQUI	I MJV1 MJSFS I RET MJ90 I RET MJ91 U WJ601 D MJV3 MJSFLL 16 MJV4 WJSFLU	AND GET UPPER FREQUE	I NJV1 MJSFE I RET MJ90 I RET MJ91 I RET MJ91 U NJ662 D HJV4, WJSFUL	ER LIMIT GREATER THA	D, MJVS, WJSFLU LY, WJV4, WJVS LY, WJ603 GT, WJ603 B, MJVS, WJSFLL R, WJ601	AND GET PREQUENCY II	I HUVI HUSFI I RET HUSFI II RET HUSS RE HUSOS 4 IS HUSOS 4 IT HUSOS 9 IT HUSOS 9 IS HUSOS 1 IS HUSOS 1 IS HUSOS 1
	D IMAGE	STR LDR BAL DS	T TITLE	10R BAL BRCL BRCL STR STR DS	T TITLE	LDR BAL BRCL EAL BRCL STR STR DS	SURE UPP	LDR CAP BRCL LDR LDR CAP BRCL	T TITLE	LDR BAL BAL BARCL CARP CARP BRRCL CARP CARP CARP CARP CARP DSTR
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03/18/77			TITLE	•					
TIME: 16:43:42		STRENGTH	GET ADDRESS OF SIGNAL STRENGTH ILLEGAL ENTRY COMPARE HITH MAX VALUE ILLEGAL TTH MAX VALUE COMPARE COUNT WITH MAX ILLEGAL TOO LARGE CONVERT BITH MAX ILLEGAL TOO LARGE CONVERT BCD TO HEX MULTIPLY BY 127 HENGTH IN REG 2 CONVERT BCD TO HEX MULTIPLY BY 127 HOUND SET UP DIVISOR DIVISOR DIVISOR CLEAR ALL BUT VALUE WANTED STORE DESIRED SIGNAL STRENGTH SPACE FOR PATCHES	AND GET RESPONSE	GET LOWER LIMIT (LOWER) GET LOHER LIMIT (UPPER) POSITION FREQUENCY FOR WJ GET CONTROL WORD 2 (FREQ UPPER) GET CONTROL WORD 1 (FREQ UPPER) CLEAR OLD FREQ (LOWER) CLEAR OLD FREQ (LOWER) FUT IN NEW FREQ (LOWER) FUT IN NEW FREQ (LOWER) SAVE NEW CONTROL WORD 1 SEND / RECEIVE NEW CONTROL WORD SPACE FOR PATCHES	NGTH WETH SET SIGNAL STRENGTH	GET RECEIVED WORD 4 CLEAR ALL BUT SIGNAL STRENGTH GET SPECIFIED SIGNAL STRENGTH COMPARE RECEIVEE WITH SPECIFIED FIND SPACE FOR PATCHES	AGAIN	GET LAST FREQ (LOWER) GET LAST FREQ (UPPER) POSITION FOR INCREMENT GLEAR ALL BUT FREQUENCY GET INCREMENT CLEAR REGISTER INCREMENT FREQUENCY
	IMAGE	TITLE AND GET SIGNAL ST	LDR I RET 4390 BRC U 44364 CMP E GT 4364 BRC GT 4364 BRC GT 8364 BRC I S 837 B	FREQUENCY TO RECEIVER	LDR D, WJVS, WJSFLL LDR D, WJVS, WJSFLU SHD D, GJV3, GJCW Z LDR D, GJV3, GJCW Z LDR D, WJV4, WJCW J LDR D, WJV4, WJV4, WJV4, WJV4, WJV5, WJV4, W	E RECEIVED'SIGNAL STRE	LDR D. WJV1, WJRS4 AND I. WJV1, O7F LDR D. WJV2, WJSFSS CMP R WJV1, HJV2 BRCL GE, WJ609	ENT FREQUENCY AND TRY	LDR D. WJV1, WJCW2 LDR D. WJV2, WJCW1 SHD R. WJV3, WJ LDR D. WJV3, WJSFIN LDR D. WJV3, WJSFIN LDR IS WJV4, O
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TIME: 16:43:42 03/18/77		GET UPPER LIMIT (UPPER) GEL UPPER LIMIT (UPPER) GEL UPPER LIMIT (UPPER) FREQ BELOW LIMIT, KEEP LOOKING HPPER PREQ MATCH, CHECK LOWERS HPPER PREQ MATCH, CHECK LOWERS INCREMENT COUNT COMPARE WITH MAX TIMES THRU BONE - NO FIND SAVENER COUNT GO START AT LOWER LIMIT AGAIN COMPARE LOWERS OF UPPER LIMIT AND FR LESS, GO START AGAIN COMPARE LOWER AGAIN GO START AGAIN COMPARE LOWER SAIN COMPARE LOWER LIMIT AGAIN COMPARE LOWER LOWER LIMIT AGAIN COMPARE LOWERS OF UPPER LIMIT AND FR GO START AGAIN COMPARE LOWERS OF UPPER LIMIT AND FR COMPARE LOWERS OF UPPER LIMIT AND FR COMPARE LOWERS OF UPPER LIMIT AND FR COMPANDATION OF THE COUNTY COMPANDATION O		GET RECEIVED FREQUENCY (DISPLAY) STORE IN CONTROL FREQ (DISPLAY) GO DISPLAY RECEIVED WORD SPACE FOR PATCHES			GET LAST RECEIVED FREQ (DISPLAY) GTORE IN CONTROL FREQ (DISPLAY) GET ADDRESS OF NO FIND MESSAGE OUTPUT MESSAGE DONE SPACE FOR PATCHES ************************************		LOAD FLAG TO INHIBIT COMPARE STORE FLAG INPUT RECEIVER CONTROL WORDS ZERO REGISTER CLEAR FLAG DISPLAY RECEIVED WORDS RETURN SPACE FOR PATCHES	
		D, HJV1, HJSFUL B, HJV2, HJSFUL GR, HJ66 BQ, HJ608 BQ, HJ608 BQ, HJ608 B, HJV1, HJ0 IS, HJV1, HO GC, HJV1, HJC	U, HJ605 R, HJ605 Lf HJ606 U hJ606		D, WJV1, WJRFL, 2 D, WJV1, WJCFL, 2 U WJ40	NE - TELL OPERATOR	D, HJV1, HJRFL, 2 D, HJV1, HJCFL, 2 I HJV1, HJSNF U HJO2 OUTPUT U HJO2	**************************************	I HJV1,01 D HJV1,CHKFLG1 I HET HJR I HJV1,0 D HJV1,CHKFLG1 U HJV0 U HJV2	**** D=7)
	RD IMAGE	LDR CCDR CDR CCL CDR CCL CCL CCL CCL CCL CCC CCC CCC CCC CC			LDRM STRN BRCL DS		LDRM STRM LDR BAL BRCL DS	* D *	LDR STR BAL 1DR STR BRCL BRCL	**************************************
	CAR			FIND	4 3609	NO FI	¥J610	. ***** . RECEI	¥J70	**************************************
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03/18/77			* * * * * * *					* * *
:: 16:43:42			**************************************	ADDRESS EYBOARD	~ ~ ~ ~ ~ ~ ~ ~ ~ ~ ~ ~ ~ ~ ~ ~ ~ ~ ~	ESS CH CH	CHARACTERS	.*************************************
TIME		LOAD "ADDRESS OFF" TURN OFF INTERFACE LOAD RETURN ADDRESS RETURN TO CALLER	**************************************	SAVE THE RETURN ADI OUTPUT BUFFER GET INPUT FROM KEYE CLEAR REGISTER CLEAR REGISTER	CLEAR REGISTER GET COUNT FROM KEYHR SET UP INDEX FOR LOOP GET RETURN ADDRESS DECREHENT COUNT ILLEGAL IF NEG, NOTHING INCREMENT BUFFER POINTER GET ONE CHARACTER	COURT CHARACTER I COMPARE WITH ASCII ILLEGAL CHARACTER I CLEAR OPPER 12 FITS POSITION ENTRY FOR	DECREMENT COUNT KEEP GOING LE HORE INCREMENT RETURN AU	**************************************
		* HJV1 HJCRF LHJV1 KET HJRET	**************************************	RET 4190R RET 617PUT RET KEYMR S'HJV4,0	RX HJV2 HJV5, HJV1 RX HJV7 KJV5, HJV1 RX HJV7 KJV2 DS REI GJ90R RX HJV7, -1 IS KJV1 I	######################################	S, WJV7 - 1 N, WJ901 S, RET 2	**************************************
	CARD INAGE	**************************************	**************************************	90 STR BAL EAL LDR	10R 10R 10R 10R 10R 10D 10D 10D 10D 10D	PER CHICAGO	ADD BRCL ADD BRC	**************************************
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